WEIGHT FUNCTIONS ON NON-ARCHIMEDEAN SPACES AND THE KONTSEVICH-SOIBELMAN SKELETON

LECTURE NOTES FOR THE 2013 SIMONS SYMPOSIUM ON NON-ARCHIMEDEAN AND TROPICAL GEOMETRY

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ABSTRACT. These are the notes for a lecture given at the Simons Symposium on non-Archimedean and tropical geometry (Virgin Islands, March 31 – April 6, 2013). The material for the lecture was based on my joint paper with Mircea Mustată with the same title (arXiv:1212.6328).

1. INTRODUCTION

1.1. The work of Kontsevich and Soibelman.

(1.1.1) In [KS06], Kontsevich and Soibelman proposed a new interpretation of homological mirror symmetry based on non-archimedean geometry over the field of complex Laurent series $\mathbb{C}((t))$. Their main idea was to encode the geometry of a one-parameter degeneration of complex Calabi-Yau varieties into a topological manifold endowed with a Z-affine structure with singularities, and to interpret mirror symmetry as a certain combinatorial duality between such manifolds. They worked out in detail the case of degenerations of K3-surfaces. These ideas were further developed by Gross and Siebert in their theory of toric degenerations. Gross and Siebert replaced the use of non-Archimedean geometry by methods from tropical and logarithmic geometry in order to extend the results of Kontsevich and Soibelman to higher-dimensional degenerations.

(1.1.2) An essential ingredient of the construction of Kontsevich and Soibelman is the following. We denote by Δ a small disc around the origin of the complex plane and we set $\Delta^* = \Delta \setminus \{0\}$. We denote by t a local coordinate on Δ centered at 0. Let X be a smooth projective family of varieties over Δ^* and let ω be a relative differential form of maximal degree on the family $X \to \Delta^*$. Kontsevich and Soibelman associated to these data a skeleton $Sk(X, \omega)$, which is a topological subspace of the Berkovich analytication of the $\mathbb{C}((t))$ -variety obtained from X by base change. If X is a family of Calabi-Yau varieties, then we set $Sk(X, \omega) = Sk(X)$ where ω is any relative volume form on X. This definition does not depend on the choice of ω .

(1.1.3) Kontsevich and Soibelman proved that $\operatorname{Sk}(X, \omega)$ can explicitly be computed on any strict normal crossings model \mathscr{X} for X over Δ : it is a union of faces of the Berkovich skeleton $\operatorname{Sk}(\mathscr{X})$ of the model \mathscr{X} . Their proof relied on

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the Weak Factorization Theorem. It is interesting to note that, even though the Berkovich skeleton $\operatorname{Sk}(\mathscr{X})$ heavily depends on the chosen model \mathscr{X} , the Kontsevich-Soibelman skeleton $\operatorname{Sk}(X, \omega)$ only depends on X and ω . Thus it singles out certain faces of $\operatorname{Sk}(\mathscr{X})$ that must appear in the skeleton of *every* strict normal crossings model.

(1.1.4) We extended this construction to varieties over complete discretely valued fields K of arbitrary characteristic. Our approach does not use the Weak Factorization Theorem but only relies on basic computations on valuations and canonical sheaves. Moreover, we proved that the skeleton of a Calabi-Yau variety over $\mathbb{C}((t))$ is always connected. An interesting gadget that appears in our work is the weight function

$$\operatorname{wt}_{\omega}: X^{\operatorname{an}} \to \mathbb{R} \cup \{+\infty\}$$

associated to a smooth and proper K-variety X and a differential form of maximal degree ω on X. This weight function is piecewise affine on the Berkovich skeleton of any strict normal crossings model of X and strictly increasing as one moves away from the Berkovich skeleton. The Kontsevich-Soibelman skeleton is precisely the set of points where wt_{ω} reaches its minimal value; see Section 3.

1.2. Log discrepancies in birational geometry.

(1.2.1) Our approach is inspired by interesting analogies with some fundamental invariants in birational geometry. Let X be a smooth complex variety and \mathcal{I} a coherent ideal sheaf on X. Let v be a divisorial valuation on X, that is, a positive real multiple of the discrete valuation on the function field $\mathbb{C}(X)$ associated to a prime divisor E on a smooth birational modification Y of X. We denote by N the multiplicity of the scheme $Z(\mathcal{IO}_Y)$ along E and by $\nu - 1$ the multiplicity of E in the relative canonical divisor $K_{Y/X}$. We set

$$\operatorname{wt}_{\mathcal{I}}(v) = \frac{\nu}{N}$$

and we call this positive rational number the weight of \mathcal{I} at v. Then the infimum of the set of weights of \mathcal{I} at all divisorial valuations v on X is called the log-canonical threshold of the pair (X,\mathcal{I}) and denoted by $lct(X,\mathcal{I})$. This is a measure for the singularities of the zero locus $Z(\mathcal{I})$ of \mathcal{I} on X, and one of the most important invariants in birational geometry. We refer to [Ko95] for more background.

(1.2.2) It is a fundamental fact that the log-canonical threshold of (X, \mathcal{I}) can be computed on a single log-resolution of (X, \mathcal{I}) , i.e., a proper birational morphism $h: Y \to X$ such that Y is smooth, h is an isomorphism over the complement of $Z(\mathcal{I})$, and $K_{Y/X}$ and $Z(\mathcal{IO}_Y)$ are strict normal crossing divisors on Y. Namely, we have

$$lct(X,\mathcal{I}) = \min\{wt_{\mathcal{I}}(v)\}\$$

where v runs over the divisorial valuations associated to the prime components of $Z(\mathcal{IO}_Y)$. If this minimum is reached on a prime component E of $Z(\mathcal{IO}_Y)$, then we say that E computes the log-canonical threshold of (X, \mathcal{I}) . If we denote by \mathcal{E} the union of such prime components E, then the Connectedness Theorem of Shokurov and Kollár states that for every point x of $Z(\mathcal{I})$ and every sufficiently small open neighbourhood U of x in $Z(\mathcal{I})$, the topological space $h^{-1}(U) \cap \mathcal{E}$ is connected. This

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was the main source of inspiration for our theorem on the connectedness of the skeleton of a Calabi-Yau variety over $\mathbb{C}((t))$ (Theorem 3.3.2).

(1.2.3) In [BFJ08] and [JM11], a closely related variant of the weight function $\operatorname{wt}_{\mathcal{I}}$ was extended from the set of divisorial valuations on X to the non-archimedean link of $Z(\mathcal{I})$ in X, that is, the analytic space over the field \mathbb{C} with the trivial absolute value that we obtain by removing the generic fiber of the \mathbb{C} -variety $Z(\mathcal{I})$ from the generic fiber of the formal completion of X along $Z(\mathcal{I})$. We have made a similar construction to define weight functions on analytic spaces over discretely valued fields; see Section 3.

2. The Kontsevich-Soibelman skeleton

2.1. Birational and divisorial points.

(2.1.1) We fix some notation for the remainder of these notes. Let R be a complete discrete valuation ring with maximal ideal \mathfrak{m} , residue field k and quotient field K. We denote by v_K the discrete valuation $K^* \to \mathbb{Z}$. We define an absolute value on K by setting $|x| = \exp(-v_K(x))$ for each element x of K^* . We denote by X a connected, smooth and proper K-variety of dimension n and by ω a non-zero differential form of degree n on X.

(2.1.2) We denote by X^{an} the Berkovich analytification of X and by $i: X^{an} \to X$ the analytification morphism. The set Bir(X) of birational points of X^{an} is defined as the inverse image under i of the generic point of X. It can be identified in a natural way with the set of real valuations on the function field K(X) that extend the discrete valuation v_K on K: the valuation associated to $x \in Bir(X)$ is given by

$$K(X)^* \to \mathbb{R} : h \mapsto -\ln|h(x)|.$$

We endow Bir(X) with the topology induced by the Berkovich topology on X^{an} .

(2.1.3) An *R*-model of *X* is a flat separated *R*-scheme of finite type \mathscr{X} endowed with an isomorphism of *K*-schemes $\mathscr{X}_K \to X$. Note that we do not impose any properness condition on the model. Let \mathscr{X} be a regular *R*-model of *X* and denote by $\widehat{\mathscr{X}}$ its formal \mathfrak{m} -adic completion. Then the generic fiber $\widehat{\mathscr{X}}_{\eta}$ of $\widehat{\mathscr{X}}$ is an analytic domain in X^{an} and we can consider the reduction map

$$\operatorname{red}_{\mathscr{X}}:\widehat{\mathscr{X}_{\eta}}\to\mathscr{X}_k.$$

If E is an irreducible component of the special fiber \mathscr{X}_k with generic point ξ , then the fiber $\operatorname{red}_{\mathscr{X}}^{-1}(\xi)$ consists of a unique point, which we call the divisorial point associated to (\mathscr{X}, E) . It is the birational point on X that corresponds to the discrete valuation on K(X) with valuation ring $\mathcal{O}_{\mathscr{X},\xi}$, normalized in such a way that it extends the discrete valuation v_K on K. We will denote the set of divisorial points (associated to all couples (\mathscr{X}, E) as above) by $\operatorname{Div}(X) \subset \operatorname{Bir}(X)$.

2.2. Definition of the skeleton.

(2.2.1) Let \mathscr{X} be a regular *R*-model of *X*, *E* an irreducible component of \mathscr{X}_k and *x* the divisorial point on X^{an} associated to (\mathscr{X}, E) . The relative canonical sheaf $\omega_{\mathscr{X}/R}$ is a line bundle on \mathscr{X} that extends to canonical line bundle $\omega_{X/K}$ on *X*. The differential form ω on *X* defines a rational section of $\omega_{\mathscr{X}/R}$ and thus a divisor $\operatorname{div}_{\mathscr{X}}(\omega)$ on \mathscr{X} . We denote by *N* the multiplicity of *E* in \mathscr{X}_k and by $\nu - 1$ the multiplicity of *E* in $\operatorname{div}_{\mathscr{X}}(\omega)$. We define the weight of ω at *x* by the formula

$$\operatorname{wt}_{\omega}(x) = \nu/N$$

and the weight of X with respect to ω by

$$\operatorname{wt}_{\omega}(X) = \inf\{\operatorname{wt}_{\omega}(x) \mid x \in \operatorname{Div}(X)\}.$$

(2.2.2) A divisorial point x on X^{an} is called ω -essential if the weight function wt $_{\omega}$ reaches its minimal value at x, that is,

$$\operatorname{wt}_{\omega}(X) = \operatorname{wt}_{\omega}(x).$$

The skeleton $\operatorname{Sk}(X, \omega)$ of the pair (X, ω) is defined as the closure in $\operatorname{Bir}(X)$ of the set of ω -essential divisorial points. If the geometric genus of X is equal to one, then we set $\operatorname{Sk}(X) = \operatorname{Sk}(X, \omega)$ where ω is any non-zero differential form of degree n on X. This definition is independent of the choice of ω , since multiplying ω by an element λ of K^* shifts the weight function by $v_K(\lambda)$.

(2.2.3) It is obvious from the definition that $Sk(X, \omega)$ is a birational invariant of the pair (X, ω) , since the spaces Bir(X) and Div(X) and the weight function wt_{ω} are birational invariants.

3. The weight function and the Connectedness Theorem

3.1. Definition and properties of the weight function.

(3.1.1) Without some suitable assumptions on the existence of resolutions of singularities, we cannot say much more about the skeleton $Sk(X, \omega)$; for instance, we cannot prove that $Sk(X, \omega)$ is non-empty. Therefore, we will assume from now on that k has characteristic zero or X is a curve. With the current state of affairs, these are the cases where resolution of singularities is known in the form that we need. In particular, it is known that every proper R-model of X can be dominated by an *sncd*-model of X, that is, a regular proper R-model \mathscr{X} whose special fiber \mathscr{X}_k is a divisor with strict normal crossings.

(3.1.2) To any *sncd*-model \mathscr{X} of X, one can associate its Berkovich skeleton $\operatorname{Sk}(\mathscr{X})$ in X^{an} . It is the set of all birational points on X such that the associated valuation is monomial with respect to the strict normal crossings divisor \mathscr{X}_k on \mathscr{X} . This skeleton is canonically homeomorphic to the dual intersection complex of the divisor \mathscr{X}_k . Thus the vertices of $\operatorname{Sk}(\mathscr{X})$ correspond to the irreducible components of \mathscr{X}_k (they are precisely the divisorial points associated to these components), and the faces of $\operatorname{Sk}(\mathscr{X})$ correspond to the connected components of intersections of sets of irreducible components of \mathscr{X}_k . The embedding of $\operatorname{Sk}(\mathscr{X})$ in X^{an} has a canonical continuous retraction

$$\rho_{\mathscr{X}}: X^{\mathrm{an}} \to \mathrm{Sk}(\mathscr{X}).$$

If f is a non-zero rational function on X, then the function

$$\operatorname{Sk}(\mathscr{X}) \to \mathbb{R} : x \mapsto -\ln|f(x)|$$

is continuous and piecewise affine.

Theorem 3.1.3. There exists a unique smallest function

$$\operatorname{wt}_{\omega}: X^{\operatorname{an}} \to \mathbb{R} \cup \{+\infty\}$$

with the following properties.

- (1) The function wt_{ω} is lower semi-continuous.
- (2) Let \mathscr{X} be an sncd-model for X and x a point of the Berkovich skeleton $\operatorname{Sk}(\mathscr{X})$. Let f be a rational function on \mathscr{X} such that, locally at $\operatorname{red}_{\mathscr{X}}(x)$, we have

$$\operatorname{div}(f) = \operatorname{div}_{\mathscr{X}}(\omega) + (\mathscr{X}_k)_{\operatorname{red}}.$$

Then

$$\mathrm{wt}_{\omega}(x) = -\ln|f(x)|.$$

In particular, wt_{ω} is continuous and piecewise affine on $Sk(\mathscr{X})$, and we get the same value as before on divisorial points. Moreover, for all x in X^{an} , we have

$$\operatorname{wt}_{\omega}(x) \ge \operatorname{wt}_{\omega}(\rho_{\mathscr{X}}(x))$$

with equality if and only if $x \in Sk(\mathscr{X})$.

(3) The restriction of wt_{ω} to Bir(X) is a birational invariant of (X, ω) .

3.2. Computation of the skeleton.

(3.2.1) We can use the properties of the weight function in Theorem 3.1.3 to compute the Kontsevich-Soibelman skeleton $Sk(X,\omega)$ on an *sncd*-model \mathscr{X} of X. The theorem immediately implies that $Sk(X,\omega)$ is the subspace of the compact space $Sk(\mathscr{X})$ consisting of the points where the continuous function $wt_{\omega}|_{Sk(\mathscr{X})}$ reaches its minimal value. In particular, $Sk(X,\omega)$ is a non-empty compact topological space. We can make this description much more explicit, as follows.

(3.2.2) We write $\mathscr{X}_k = \sum_{i \in I} N_i E_i$. For each $i \in I$, we denote by $\nu_i - 1$ the multiplicity of E_i in the divisor $\operatorname{div}_{\mathscr{X}}(\omega)$. Recall that each face of $\operatorname{Sk}(\mathscr{X})$ corresponds to a connected component C of an intersection $\bigcap_{j \in J} E_j$ where J is a non-empty subset of I. We say that the face is ω -essential if

$$\frac{\mu_j}{N_j} = \min\{\frac{\mu_i}{N_i} \mid i \in I\}$$

and C is not contained in the closure in \mathscr{X} of the canonical divisor $\operatorname{div}_X(\omega)$ (the divisor of zeroes of ω on the K-variety X).

Theorem 3.2.3. The weight of X with respect to ω is given by

$$\operatorname{wt}_{\omega}(X) = \min\{\frac{\mu_i}{N_i} \mid i \in I\}$$

and the skeleton $Sk(X, \omega)$ is the union of the ω -essential faces of $Sk(\mathscr{X})$.

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(3.2.4) Here's an interesting example. Suppose that $R = \mathbb{C}[[t]]$ and that X is a K3-surface over K. Assume that X has an *sncd*-model \mathscr{X} such that \mathscr{X}_k is reduced and $\omega_{\mathscr{X}/R}$ is trivial. Such models played an important role in the classification of semi-stable degenerations of K3-surfaces by Kulikov and Persson-Pinkham. They have the special property that $\mathrm{Sk}(X) = \mathrm{Sk}(\mathscr{X})$, since all multiplicities N_i are equal to one and all ν_i are equal, for any choice of volume form ω on X, by the triviality of $\omega_{\mathscr{X}/R}$.

3.3. The Connectedness Theorem.

(3.3.1) Our main result is the following variant of the Shokurov-Kollár Connectedness Theorem. Like the proofs of Shokurov and Kollár, our proof is based on vanishing theorems: we deduced generalizations of Kawamata-Viehweg Vanishing and Kollár's Torsion-free Theorem for varieties over power series rings in characteristic zero by means of Greenberg approximation.

Theorem 3.3.2 (Connectedness Theorem). If X is a geometrically connected, smooth and proper K-variety of geometric genus one, then Sk(X) is connected.

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