

T. Bridgeland - Stability & Derived Categories

11/14/02

Stability condition on a triangulated category - notion from physics.
idea of M.R. Douglas on D-branes: Dirichlet branes, homological mirror symmetry & stability (IM)

Space of stability conditions is roughly complex moduli of mirror variety...

Example: X smooth proj. curve / $\mathbb{C}$

$\text{Coh}(X)$ - category of coherent sheaves on X

$E = T \oplus F$ T = torsion, F = locally free

(more canonically an extension $T \hookrightarrow E \twoheadrightarrow F$ splits)

T is finite length (extensions of skyscrapers)

$K(X) = K(\text{Coh}(X)) \xrightarrow[\text{rank}]{\deg} \mathbb{Z} \times \mathbb{Z}$ $\text{rank}(T)=0$ $\deg(T)=\text{length}$

Slope of $E \neq 0$ $\mu(E) = \deg(E)/\text{rk}(E)$, $\mu(T) = +\infty$.

$0 \neq E \in \text{Coh}(X)$ is (semi)stable if for any $0 \neq A \subsetneq E$

one has $\mu(A) \leq \mu(E)$ ($<$)

• All torsion sheaves are semistable, stable iff skyscraper

• semistable $\rightarrow$ vector bundle or torsion

... if E not torsion slope $< \infty$ so can't have torsion subobject to be semistable

Any $0 \neq E \in \text{Coh } X$ has a Harder-Narasimhan filtration

$0 = E_0 \subset E_1 \subset \dots \subset E_{n-1} \subset E_n = E$ with each $F_i = E_i/E_{i-1}$

semistable $\mu(F_1) > \mu(F_2) > \dots > \mu(F_n)$

— uniquely defined ...

eg E semistable $\rightarrow E = E_1$.

— any chain $\dots \subset E_2 \subset E_1 \subset E$ with $\mu(E_i) \geq \mu(E_{i-1})$ must stabilize

rank has to stabilize

Construction: $E_1 =$ subobject with largest slope.

• Category of semistable objects of fixed slope is finite length

— all generalizes to abelian category with slope function. [char 0 not necessary]

Consider the triangulated category $D(X) = D^b(\text{Coh } X)$
with truncation functor $\tau_{\leq i}$:

$$\tau_{\leq i}: (\dots \rightarrow M^{i-1} \xrightarrow{d^{i-1}} M^i \xrightarrow{d^i} M^{i+1} \rightarrow \dots) \\ = (\dots \rightarrow M^{i-1} \xrightarrow{d^{i-1}} \ker d^i \rightarrow 0 \rightarrow \dots)$$

$$\text{Then } H^j(\tau_{\leq i} E) = \begin{cases} H^j(E) & j \leq i \\ 0 & j > i \end{cases}$$

$$\text{Triangles } \tau_{\leq i+1} E \rightarrow \tau_{\leq i} E \\ \downarrow \quad \quad \downarrow \\ \text{deg } 1 \quad \dots \quad H^i E[-i]$$

$$\text{In } D^b(X): \quad 0 = \tau_{\leq N} E \rightarrow \tau_{\leq N-1} E \rightarrow \dots \rightarrow \tau_{\leq N+1} E \rightarrow \tau_{\leq N} E = E \\ N \gg 0$$

$\downarrow \quad \quad \quad \downarrow$
 $H^{-(N-1)} E[-N+1] \quad \quad \quad H^N E[-N]$

Canonical filtration, way to construct object from extensions of sheaves. no morphisms between the steps.

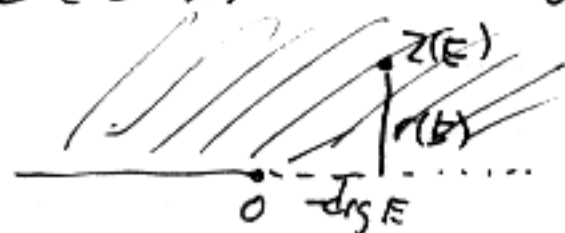
$$\text{Write Harder-Narasimhan in same way} \quad 0 = E_0 \subset E_1 \subset \dots \subset E_{n-1} \subset E_n = E \\ 0 = E_0 \xrightarrow{F_0} E_1 \xrightarrow{F_1} E_2 \rightarrow \dots \rightarrow E_{n-1} \xrightarrow{F_{n-1}} E_n = E$$

$\downarrow \quad \quad \downarrow \quad \quad \downarrow \quad \quad \downarrow$
 $F_1 \quad \quad F_2 \quad \quad \quad F_n$

Combining these two ideas gives a filtration of any $0 \neq E \in D(X)$ by shifts of semistable sheaves.

Define a linear map $Z: K(X) \rightarrow \mathbb{C}$ on $\mathbb{R}^2$ ($\mathbb{R}$ appears as real part)

$$Z([E]) = -\deg E + \sqrt{-1} \operatorname{rank} E$$



→ this is where actual semistable sheaves land: $\operatorname{rank} > 0$, if $\operatorname{rank} = 0$ $\deg > 0$.

$$\text{Define } \phi(E) = \frac{1}{\pi} \arg Z(E) \in (0, 1]$$

for any $0 \neq E \in \operatorname{Coh} X$ — phase of E (phase of torsion = 0)

$$\text{Note } \phi(E_1) > \phi(E_2) \iff \mu(E_1) > \mu(E_2)$$

$$\text{Define } \phi(E[j]) = \phi(E) + j \quad \text{phase function}$$

— not defined on all objects, eg $E \oplus E(1)$ has $Z = 0 \dots$

Now any $0 \neq E \in D(X)$ has a unique filtration

$$0 = E_0 \rightarrow E_1 \rightarrow \dots \rightarrow E_{n-1} \rightarrow E_n = E \quad \text{with } A_i \text{ shifts of semistable pieces}$$

$\swarrow A_1$ $\swarrow A_n$
 with $\phi(A_1) > \dots > \phi(A_n)$
 (more naturally ϕ_i should be indices of filtered pieces).

Note $Z(E[1]) = -Z(E) \dots$

- Def** A stability condition on a triangulated category T consists of a linear map $Z: K(T) \rightarrow \mathbb{C}$, the central charge, and full subcategories $\mathcal{P}(\phi) \subset T$ for each $\phi \in \mathbb{R}$ ("semistable objects of phase ϕ ") satisfying:
- $\mathcal{P}(\phi)[1] = \mathcal{P}(\phi+1)$
 - $E \in \mathcal{P}(\phi) \Rightarrow Z(E) = m(E)e^{i\pi\phi}$ for $\text{Re } m(E) > 0$
(i.e. $Z(E)$ have phase ϕ)
 - If $\phi_1 > \phi_2$ and $E_i \in \mathcal{P}(\phi_i)$ then $\text{Hom}(E_1, E_2) = 0$
no maps to objects of smaller slope
 - $\forall \phi \in \mathbb{R}$ there are real numbers $\phi_1 > \phi_2 > \dots > \phi_n$ and a filtration $0 = E_0 \rightarrow E_1 \rightarrow \dots \rightarrow E_{n-1} \rightarrow E_n = E$
 $\swarrow A_1$ $\swarrow A_n$
 with $A_i \in \mathcal{P}(\phi_i) \quad 1 \leq i \leq n$
 - $Z(\bigcup_{\phi \in \mathbb{R}} \mathcal{P}(\phi)) \subset \mathbb{C}$ has no limit points. "finite mass gap"

... objects in $\mathcal{P}(\phi)$ are the branes.
 Following from axioms that filtration is unique in (d)
 $|Z| = \text{mass of the brane}$

Define $\phi^+(E) = \phi_1$, $\phi^-(E) = \phi_n$ smallest argument

$\phi^+(E) = \phi^-(E) \iff E$ is semistable of phase $\phi^+(E)$.

Define "mass" $m(E) = \sum |Z(A_i)|$. $m(E) \geq |Z(E)|$, equality if E semistable.

Let $\Sigma(T)$ be the set of stability conditions on T up to equivalence (equivalent if semistable objects are semistable of same phase & mass in other.)

Distance: $d(\sigma_1, \sigma_2) = \sup_{0 \neq E \in \mathcal{T}} \left\{ |\phi_{\sigma_1}^+(E) - \phi_{\sigma_2}^+(E)|, |\phi_{\sigma_1}^-(E) - \phi_{\sigma_2}^-(E)|, \log \left| \frac{m_{\sigma_1}(E)}{m_{\sigma_2}(E)} \right| \right\} < \infty$

$d(\sigma_1, \sigma_2) = 0 \Rightarrow \sigma_1 = \sigma_2$

action of autoequivalences of the category $\mathcal{T}$ by isomorphisms $\mathbb{Z}$ of $GL^+(2, \mathbb{R})_+$

$\Sigma(\mathcal{T}) \rightarrow K(\mathcal{T}, \mathbb{Z}) \quad (Z, \rho) \rightarrow Z$ is "coring rep"

Def A slope function on an abelian category $\mathcal{A}$ is a linear map $Z: K(\mathcal{A}) \rightarrow \mathbb{C}$ such that $0 \neq E \in \mathcal{A} \Rightarrow$

$\text{Im } Z(E) > 0$ or $\text{Im } Z(E) = 0$ & $\text{Re } Z(E) < 0$

Proposition A stability condition on a triangulated category $\mathcal{T}$ determines a bounded nondegenerate t-structure on $\mathcal{T}$ & a slope function on its heart. Conversely a bounded nondegenerate t-structure with a discrete slope function determines a stability condition $\hookrightarrow$ image is discrete

t-structure on $\mathcal{T}$: full subcategory $\mathcal{T}^{\leq 0}$ with $\mathcal{T}^{\leq 0}[1] \in \mathcal{T}^{\leq 0}$ s.t. inclusion $\mathcal{T}^{\leq 0} \subset \mathcal{T}$ has right adjoint $\Rightarrow$ decomposition $A \rightarrow E \xleftarrow{f, g} B$, $\text{Hom}(\mathcal{T}^{\leq 0}, \mathcal{B}) = 0$

Semiorthogonal decompositions give $\mathcal{T}$ structures.

Nondegeneracy: $\bigcap \mathcal{T}^{\leq 0}[i] = 0$

$\Leftrightarrow$ object is nonzero iff nonzero object has a nonzero cohomology.

Given a stability condition & an interval $I \subset \mathbb{R}$ define $\mathcal{P}(I)$ to be the set of objects E with $\phi_i(E) \in I$ $1 \leq i \leq n$
 $\Rightarrow \mathcal{P}(I)$ is a t-structure for any $I \subset \mathbb{R}$
 - Family of t-structures parametrized by real numbers, compatible with translation

t-structure on $\mathcal{T}$ gives categories $\dots \subset \mathcal{T}^{\leq 0} \subset \mathcal{T}^{\leq 1} \subset \dots$
 "Slope" on $\mathcal{T}$. Now we have categories $\mathcal{T}^{\leq a}$ for $a \in \mathbb{R}$ $a < b$ $\mathcal{T}^{\leq a} \subset \mathcal{T}^{\leq b}$, etc., repeatable with shift by 1.

- follows from stability condition, by forgetting mass info & linearity of Z function

Heart of $\mathcal{P}(>0)$ is $\mathcal{P}(0,1]$, precisely things
referred to upper half plane

$\mathbb{Z}$ of twistables has discrete image attachedly
but not necessarily for linear combinatorics.

$\widetilde{GL}^+(2, \mathbb{R}) = \{ (f, T) : f: \mathbb{R} \rightarrow \mathbb{R} \text{ increasing, } f(t+1) = f(t)+1 \text{ \& } T \in GL^+(2, \mathbb{R}) \}$
universal cover of $GL^+(2, \mathbb{R})$ positive determinant s.t. f lifts T on space S' of rays in $\mathbb{R}^2$ to $\mathbb{R}$

This acts by $\mathcal{P}'(\phi) = \mathcal{P}(f(\phi))$, $Z' = T^{-1} \circ Z$

Translation part: $f(t) = t + a$: just moving phases,
rotating central charges. 360° rotation $\leftrightarrow$ table
shift $E \mapsto E[2]$.

Action on heart is tilting $\mathcal{P}(0,1] \rightarrow \mathcal{P}(0,1]$

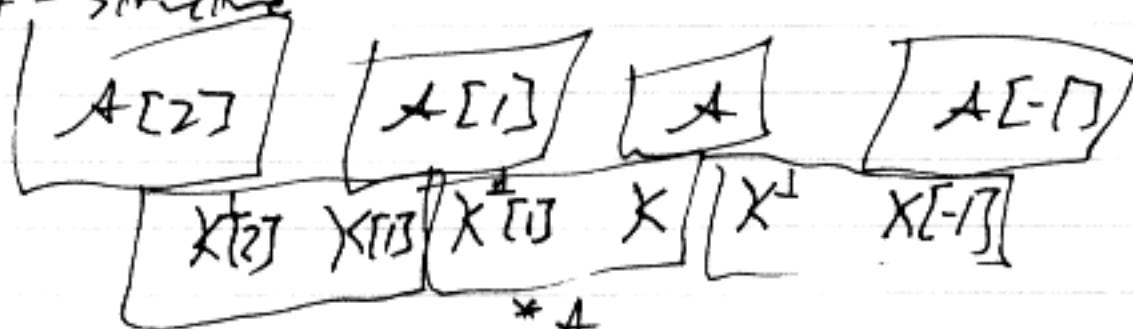
Def A torsion theory in an abelian category $\mathcal{A}$ is
a full subcategory $\mathcal{K} \subset \mathcal{A}$ such that if $\mathcal{K}^\perp = \{ A \in \mathcal{A} : \text{Hom}_{\mathcal{A}}(K, A) = 0 \ \forall K \in \mathcal{K} \}$
then every $E \in \mathcal{A}$ has a decomposition
 $0 \rightarrow K \rightarrow E \rightarrow L \rightarrow 0$ with $K \in \mathcal{K}$, $L \in \mathcal{K}^\perp$.

" $\mathcal{K}$ = torsion classes, $\mathcal{K}^\perp$ = torsion free classes"

Suppose $\overline{\mathcal{T}}^{so} \subset \mathcal{T}$ is a t-structure & $\mathcal{K} \subset \mathcal{A}$ is
a torsion theory on its heart $\Rightarrow$ new t-structure

${}^*\mathcal{T}^{so} \subset \mathcal{T}$ defined by $E \in {}^*\mathcal{T}^{so}$ iff $H^i(E) = 0$ $i > 0$
& $H^0(E) \in \mathcal{K}$.

Given $\mathcal{T}$ triangulated $\supset$ thick subcategory, t-structures
which restrict to t-structures on sub $\leftrightarrow$ t-structure on
sub & quotient, can shift each $\Rightarrow$ perverse
t-structure



no lens going
this way

So as we translate stability structure get continuous family of tilts!

Fix μ , X a curve, $\mathcal{A}_\mu = \mathcal{D}(X)$ defined by
 $E \in \mathcal{A}_\mu \iff H^i(E) = 0$ unless $i=0$ or -1 ,
 $1-H$ factors of $H^*(E)$ have slope $\leq \mu$
 $" \quad " \quad " \quad H^0(E)$ have slope $> \mu$

In here stable objects of slope μ are simple --
 equivalent to category of modules on NC scheme (Schroeder)
 NC moduli of sheaves of this slope.

-- simple objects are precisely stable vector bundles
 of slope μ ! -- instead of things supported at points...

$\mathcal{A}^\mu \iff$ sheaves on NC scheme! can have Ext between
 objects supported at different points (space =
 moduli of stable bundles, with different
 points comparable... have Ext's.

- whole derived category here is derived of this abelian
 $\iff$ modules over an NC algebra, endos of a projective
 generator.

X on elliptic curve, $K(X)$ is not finite rank group ($\mathbb{Z} + \text{Pic } X$)
 - degree & determinant.

A stability condition is numerical if
 $\chi(-) = \chi(\Theta, -)$ for some $\Theta \in K(X) \otimes \mathbb{R}$

$$\chi(E, F) = \sum (-1)^i \text{Ext}_X^i(E, F)$$

- ie factors via Chern character $K(X) \xrightarrow{\chi} \mathbb{Q}$
 $\uparrow$
 $\text{ch} \rightarrow H^*(X, \mathbb{Q})$

$\text{Stab}(X)$ = set of numerical stability conditions

- closed subspace of all stability conditions

Prop The action of $\text{GL}^+(2, \mathbb{R})$ on $\text{Stab } X$ is
 free & transitive so $\text{Stab } X \cong \text{GL}^+(2, \mathbb{R})$
 (true for any curve genus > 0)

Strong Maximal! want $\frac{\text{Stab } X}{\text{Aut } \mathcal{D}(X)} = \frac{\text{GL}^+(2, \mathbb{R})}{\text{SL}(2, \mathbb{Z})} \cong \mathcal{H} / \text{SL}_2 \mathbb{Z}$
 $\text{Aut } \mathcal{D}(X)$

ie. $\text{Stab } X/\text{Aut } O(X) \stackrel{cc}{=} \text{"space of deformations of the mirror"}$
 is in this case elliptic curves + 1-form.

Deformation

Lemma If $\sigma_1, \sigma_2 \in \Sigma(\tau)$ have the same central charge Z
 then $d(\sigma_1, \sigma_2) \geq 1$

$$\Sigma(\tau) \xrightarrow{Z} [K(\tau) \otimes \mathbb{C}]^\vee \quad \text{fibers are discrete}$$

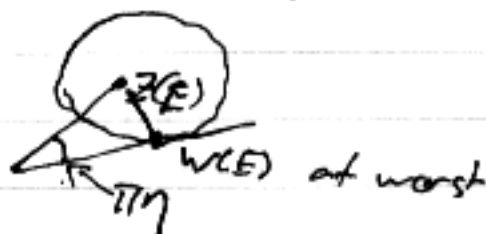
Def Let $\sigma = (Z, \gamma)$ be a stability condition on $\mathcal{T}$.

A perturbation of σ with parameter ε is a linear map $W: K(\tau) \rightarrow \mathbb{C}$ s.t.

- $|W(E) - Z(E)| < \varepsilon / |Z(E)|$ for all $E \in \bigcup_{\phi \in \mathbb{R}} \mathcal{P}(\phi)$
- $W(\bigcup_{\phi \in \mathbb{R}} \mathcal{P}(\phi)) \subset \mathbb{C}$ has no limit points. -- apply to all family

Let $\eta = \frac{1}{\pi} \sin^{-1}(\varepsilon)$

- phase can change by at most η



An object $0 \neq E \in \mathcal{T}$ is light if $\phi^+(E) - \phi^-(E) < 1 - 2\eta$.

For any such $\exists$ well defined branch of $\psi(E) = \frac{1}{\pi} \arg W(E) \in (\phi^-(E) - \eta, \phi^+(E) + \eta)$



all stars lie in half plane, just follow them around town.

Def E is W-stable if there is no triangle of light objects $A \rightarrow E \leftarrow B$ with $\psi(A) > \psi(E) > \psi(B)$

Theorem If $\mathcal{Q}(\psi)$ denotes the subcategory of W-stable objects of phase ψ then $(W, \mathcal{Q})$ is a stability condition on $\mathcal{T}$.

T. Bridgeland II

Sheaves on K3

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K3: projective smooth surface X with $\omega_X = \mathbb{Q}$
trivial canonical bundle, & $H^1(X, \mathbb{Q}) = 0$

Properties: $H^2(X, \mathbb{Z}) = \mathbb{Z}^{\oplus 22}$ with intersection pairing signature $(3, 19)$

Mukai - extend to $H^{2*}(X, \mathbb{Z}) = H^0(X, \mathbb{Z}) \oplus H^2(X, \mathbb{Z}) \oplus H^4(X, \mathbb{Z})$
" " " "

$\langle (r_1, D_1, s_1), (r_2, D_2, s_2) \rangle = D_1 \cdot D_2 - r_1 s_2 - r_2 s_1$: add hyperbolic plane, get Mukai lattice in 24-dim space

Torelli: Two K3s are isomorphic iff there is a Hodge isometry
 $H^2(X_1, \mathbb{Z}) \xrightarrow{\sim} H^2(X_2, \mathbb{Z})$ - preserves $(,)$
& takes $H^{2,0}(X_1) \rightarrow H^{2,0}(X_2)$

Orlov Two K3s have equivalent derived categories if extended
lattices $H^{2*}(X_i, \mathbb{Z})$ are Hodge isometric. (put $H^0(X, \mathbb{Z})$ & $H^4(X, \mathbb{Z})$ inside $H^{2,1}$)

- automorphisms of a K3 are seen as automorphisms of Hodge structure (+) positive cone ... ie index two in Hodge automorphisms.

Equivalences of derived categories given by complex or product, to which one can then assign an equivalence of cohomology groups (Chern character of universal object) commuting with Chern character maps. Can mix degrees of cohomology!

$\Phi: D(X_1) \xrightarrow{\sim} D(X_2) \Rightarrow$ Orlov: $X_1 \xleftarrow{p_1} X_1 \times X_2 \xrightarrow{p_2} X_2$

given by $Rp_{2*}(p_1^* \otimes p_1^*(-))$

Gives correspondence on cohomology $p_{2*}(ch(p_1) \cdot p_1^*(-))$
up to Todd class ... gives map

$\phi: H^*(X_1, \mathbb{Q}) \rightarrow H^*(X_2, \mathbb{Q})$

on K3 also preserves integral cohomology
- preserves difference $p-q$ in Hodge structure.

Riemann-Roch $E, F \in D(X) \Rightarrow$ relative Euler char.

$$\chi(E, F) = \sum_i (-1)^i \dim_k \operatorname{Hom}_{D(X)}^i(E, F) \quad \text{sum of ext groups}$$

$$= \int_X \operatorname{ch}(E^\vee) \operatorname{ch}(F) \operatorname{td}(X)$$

$$= -\langle v(E), v(F) \rangle \quad \text{Mukai pairing}$$

where $v(E) = (r(E), c_1(E), \underbrace{\operatorname{ch}_2(E) + r(E)}_{\text{Chern character}})$
Mukai vector rank $S(E)$

$$v: K(X) \rightarrow H^*(X, \mathbb{Z})$$

special to K3's: no denominators here, only $\frac{1}{2}c_1^2$
& intersection form on K3 is even.

Serre duality $\operatorname{Hom}_{D(X)}^i(E, F) = \operatorname{Hom}_{D(X)}^{2-i}(F, E)^\vee \quad (c_2 = c_1^2)$
 $\Rightarrow \langle, \rangle$ is symmetric

Stability: L ample line bundle on X .

$$\mu(E) = \frac{c_1(E) \cdot L}{r(E)} \quad \nu(E) = \frac{S(E)}{r(E)} = \frac{\operatorname{ch}_2 + r}{r}$$

A torsion-free sheaf E is L -stable if $\forall 0 \neq A \subsetneq E$
($\mu(A) < \mu(E)$) or ($\mu(A) = \mu(E), \nu(A) < \nu(E)$)

Faltings: a vector bundle on a curve is semistable iff
 $\exists$ another v.b. with no Homs or Exts between them
- no such condition on surfaces $\dots \Rightarrow$ more
interesting space of stability conditions.

Theorem (Mukai) Let $N(X) = K(X) / \text{numerical eq}$ - numerical lattice of X
($N(X) \hookrightarrow H^*(X, \mathbb{Z})$) $E_1 \sim E_2 \Leftrightarrow \chi(E_1, F) = \chi(E_2, F) \quad \forall F \in D(X)$
If $v \in N(X)$ is primitive then
for general ample line bundle L the moduli of
stable sheaves $M_{(X, L)}(v)$ is a smooth projective
complex symplectic variety of dim $\langle v, v \rangle + 2$

Symplectic form: $T_E M_{(X, L)}(v) = \operatorname{Ext}^1(E, E)$

$$\text{pair } \operatorname{Ext}^1(E, F) \times \operatorname{Ext}^1(E, F) \rightarrow \operatorname{Ext}^2(E, F) = \operatorname{Hom}(E, E)^\vee = \mathbb{C}$$

(E simple)

- note $\langle v, v \rangle = -\chi(E, E) = \dim \text{Ext}^1(E, E) - \dim \text{Ext}^0(E, E)$
 So $\dim M_E = \langle v, v \rangle + 2$
 $\dim \text{Ext}^2(E, E) = 1$

(Stability: look at $\chi(E \otimes L^n) / r(E)$)

E stable $\Rightarrow \langle v(E), v(E) \rangle \geq -2$

If $v(E)^2 = -2$ E is called spherical,
 moduli space is just a point! set by χ

then $\text{Ext}^0(E, E) = \mathbb{C}$, $\text{Ext}^1(E, E) = \mathbb{C}$ $\text{Ext}^2(E, E) = 0$ like sphere!

Stability conditions

$T = D(X)$ Numerical stab condition: $Z : N(X) \rightarrow \mathbb{C}$ linear
 + Subcategories $\mathcal{P}(\emptyset) \subset D(X)$ $\emptyset \in \mathbb{R}$
 $Z(\mathcal{P}(\emptyset)) \subset \mathbb{R}_{>0} e^{i\pi\emptyset}$ etc.

$\text{Stab}(X) = \text{Set of numerical stability conditions on } D(X), + \text{ topology etc.}$

There is a continuous map

$Z : \text{Stab}(X) \rightarrow [N(X) \otimes \mathbb{C}]^V$

Let $\Delta = \{ \sigma \in N(X) : \sigma^2 = -2 \}$ Mutually vectors of spherical objects

Lines in Moduli Space! (proj) from $\mathbb{R}^{2,2}$ to $\mathbb{R}^{9,2}$
 $\mathcal{P}^+(X) = \{ Z : N(X) \otimes \mathbb{R} \rightarrow \mathbb{C} : \text{Ker } Z \text{ negative definite} \}$
 $\& \text{Ker } Z \cap \Delta = \emptyset \text{ empty}$
 - one subset of $[N(X) \otimes \mathbb{C}]^V$ with 2 components

Theorem There is a connected component of $\text{Stab}(X)$ whose
 image under Z is $\mathcal{P}^+(X)$ & the induced map
 $Z : \text{Stab}^0(X) \rightarrow \mathcal{P}^+(X)$ is a covering space

Conjecture $\text{Stab}(X) \xrightarrow{Z} \mathcal{P}^+(X)$ is the universal cover

... auto automorphisms of $D(X)$ acting trivially on H^*
 are deck transformations of this covering

$\Pi_1 = \text{Ker} (\text{Aut } D(X) \rightarrow \text{Aut } H^*(X, \mathbb{Z}))$

... aut $K3$ is a complicated group, this is
 suggests that it is built up from $\text{Aut}(\text{other})$
 + $\Pi_1(\mathcal{P}^+)$ h, proper complement.

$\mathcal{P}_+$ is space where Borchers' automorphic forms live...

Why is $\mathcal{Z}$ a covering space?

Suppose $(Z, P) \in \text{stab } X$, $Z \in P^+(X)$
 Need to show that if $W = Z + \delta Z$ small deformation,
 then $|(W - Z)(E)| \leq \epsilon |Z(E)|$ for all
 stable objects E , then apply theorem from last yr.

Take an orthogonal basis of $N(X) \otimes \mathbb{R}$ $e_1, \dots, e_n$ with
 $e_1^2 = e_2^2 = 1$, $e_i^2 = -1$ $i \geq 3$ & $Z(e_i) = 0$ $i \geq 3$.

Any stable E satisfies $\langle v(E), v(E) \rangle \geq -2$

$$\Rightarrow \sum_{i \geq 3} v_i^2 \leq 2 + v_1^2 + v_2^2 \leq K |Z(u)| \text{ since } K$$

Write $W(E) = Z(E) + \langle u, v(E) \rangle$ $u \in N(X) \otimes \mathbb{C}$

$$\text{Then } |W(E) - Z(E)| = |\langle u, v(E) \rangle| \leq \|u\| \|v(E)\| \leq \epsilon |Z(u)|$$

$$\|u\| < \frac{\epsilon}{K}$$

-Very special to K3 surfaces, probably not true in general higher dim.

$\Pi(P^+)$ is generated by loops around the spherical vectors

(P^+ is hyperplane complement)

So conj gives description of $\text{Aut } K3$.

Construction of stability conditions on K3

$Z \in P^+(X)$, $Z: N(X) \otimes \mathbb{R} \rightarrow \mathbb{C}$ $\text{Ker } Z < 0$

$Z(E) = \langle \Pi, v(E) \rangle$ $\Pi \in N(X, \mathbb{C})$ by Hodge theory
 $\Pi_1 + i\Pi_2$

Π_1, Π_2 span P_2 def plane in $N(X)$...

Acting by $\text{GL}_2/\mathbb{R}$ normalize so that $\Pi_1^2 = \Pi_2^2 > 0$,
 $\langle \Pi_1, \Pi_2 \rangle = 0$.

Still have a $\mathbb{C}^*$ factor, normalize so that $Z(Q) = -1$.

-got rid of GL_2 action.

Let $P_{\text{red}}^+(X) = \{ Z = \langle \Pi_1 + i\Pi_2, - \rangle \in P^+(X) \}$
 $\Pi_1, \Pi_2, Z(Q)$ as above

$$\Rightarrow \Pi = e^{B+iJ} = (1, B+iJ, \frac{B^2-J^2}{2} + \langle B, J \rangle i)$$

$$\text{Then } Z(E) = \frac{1}{2r} (v(E)^2 - (\Delta - rB)^2 + r^2 J^2) + iJ \cdot (\Delta - rB)$$

$$\text{if } v(E) = (r, \Delta, s)$$

- need abelian category so that this lies in

→ use tilting to define t-structure compatible with $\mathbb{Z}$.

- torsion free
Define subcategories $\subset \text{Coh } X$, $X = \{E \in \text{Coh } X : \text{All H-N factors of } E/\text{tors } E \text{ have slope } > B \cdot J\}$
 $X^\perp = \{E \in \text{Coh}(X) : E \text{ torsion free, all HN factors of slope } \leq B \cdot J\}$

Slope/stability defined wrt J vector, $\mu(E) = \frac{C(E) \cdot J}{r(E)}$

- ASSUME J ample : we're working on an open subset of $\mathcal{P}^+$

Tilting gives an abelian category $\mathcal{A} \subset D(X)$.

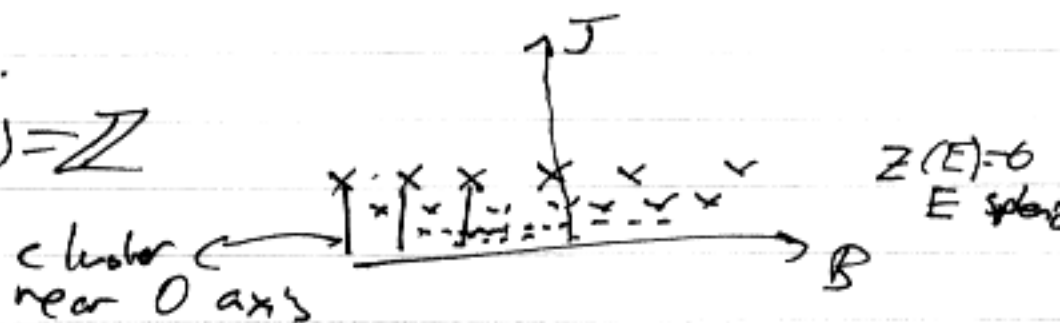
$$\mathcal{A} = \{E \in D(X) : H^0(E) \in X, H^{-1}(E) \in X^\perp, H^i(E) = 0 \text{ for } i \neq 0, -1\}$$

$\text{Im } Z(E) = r \cdot (\mu(E) - B \cdot J)$. So $\text{Im } Z(E) \geq 0$ for all $E \in \mathcal{A}$ - so this does the trick to land us in upper half plane!

What if $\mu(E) = B \cdot J$? Need such E to satisfy $Z(E) \in \mathbb{R}_{>0}$ (so that when shifted by 1 land in $\mathbb{R}_{>0}$)

- problem when $v(E) = -2 \dots$

Assume for simplicity $\text{Pic}(X) = \mathbb{Z}$



- so have to remove $\gamma \gamma \gamma$ half lines starting from these points! get large open subset

nondegenerate grand these spherical bundles should correspond to "twist functors"

... only branch cuts.

I have autoequivalence taking things out of this subset into our subset...



If E is spherical $\Rightarrow$ twist functor $\Phi_E : D(X) \rightarrow D(X)$
defined by triangle

$$\text{Hom}(E, F)^* \otimes E \rightarrow F$$

$$\downarrow$$

$$\Phi_E F$$

Claim Φ_E is equivalence

if E is spherical

--- reflection on K-theory ... need $\text{Hom}(F, E)^i = \begin{cases} 0 \\ \vdots \\ 0 \end{cases}$
(use Serre duality functor to prove autoequivalence)

- Seidel & Thomas

- Split category into E & its right orthogonal ...

$D(X)$ is like Hilbert space - can do this on 2-nd derived category

$D(X) = \langle E \rangle \perp E^\perp$, functor's identity on $E^\perp$ and $E \mapsto E[n-1]$ on $\langle E \rangle$

Acts as reflection on K theory.. its square is "monodromy" around E .

$$\Phi_E \left(\begin{matrix} E \\ X \end{matrix} \right)$$

Lemma An object $E \in D(X)$ with $r(E) > 0$, $\mu(E) > 0$ is stable in σ_{Bring} for all $n \gg 0$ (large volume limit)

$\Leftrightarrow E$ is a B-twisted stable sheaf (wrt to shift) (in Gieseker sense)

Stability condition is never Gieseker stability, only in this asymptotic direction.

In large volume limit branes are Gieseker stable sheaves.

Physics X a Calabi-Yau $\Rightarrow$ SCFT moving in new moduli space, "moduli of CFTs" - supposed to be smooth ... no global geometric picture of this moduli space.

$[X \text{ Calabi-Yau}] \Rightarrow [SCFT]$, Roughly extra data is a complex structure on X

and a complexified Kähler class $B + iJ \in H^2(X, \mathbb{C}) / H^2(X, \mathbb{Z})$.

J Kähler, B flat class up to integer shift.

- up to some discrete equivalence.

This data defines an open subset of moduli of SCFTs.

different one starts from CYs



① - open piece not coming from CYs

- get open nbhd of cusp ($T \rightarrow \infty$) from CYs
but have other things inside, eg orbifolds

Slice of things with fixed complex structure
should correspond to space of stability conditions
on $D(X)$. Mirror symmetry is auto. of the
space(?) Not preserving slice...

To each SCFT string theory associate a category
of branes - boundary conditions in this theory. B_1, B_2 branes

$$\text{Hom}(B_1, B_2) = \text{category of strings from } B_1 \text{ to } B_2$$

where Q is BRST cohomology algebra.

There is also a topological twisting of $N=2$ SCFT (K3)

to Q -cohomology, consider as CFT

$\mathcal{P}$, cat of branes in topologically twisted CFT are just $D(X)$
-- independent of other data $B+iJ$

$U(1)$
 $\phi \in \mathbb{R}$

In CY3 case all deformations of derived category are for
those of X , not true in K3 case.

Gerbe case: if the nontrivial gerbes we're looking at
any coherent sheaves or perfect complexes

- will look like quantum torus,

if not of unit get Azumaya over huge discrete

but geometrically have no f.d. reps

$|q|=1 \Rightarrow \mathcal{O}^*$ algebras...

$uv = q$

K3: $H^2(X, \mathbb{C}) \neq 0$ have gerbe deformations.

For formal deformations no problems...

In string theory, category $\mathcal{P}$ is well defined as abelian category

but inclusion $\mathcal{P} \subset D(X)$ is not, get noncommutativity!

- have a NC geometry if. As categories

but not commutative geometry - description of $D(X)$

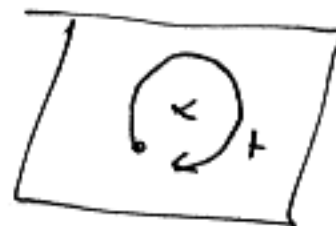
- can have different ones underlying

- String theory gives an algebra category A s.t.
 $D(A) \cong \text{~~the~~ } D(X)$

- have monodromy in this identification
 $\mathcal{P}_+$ family with embeddings

$$\begin{array}{ccc} \mathcal{P}_+ & \xrightarrow{\Phi} & D(X) \\ \parallel & & \downarrow \Phi \\ \mathcal{P}_+ & \hookrightarrow & D(X) \end{array}$$

Φ neutral automorphism -
 embedding changes by monodromy



Universal cover of moduli space should be space of deformations
 of $\mathcal{P}$ & embedding in $D(X)$.

$$K(X) = \bigoplus H^{0,p}(X) \cong H^3(X^\vee)$$

$$\begin{array}{c} \downarrow \mathbb{Z} \\ \mathbb{C} \end{array}$$

$$\begin{array}{c} \downarrow \int \Omega \\ \mathbb{C} \end{array}$$

Mirror space
 Period of
 hol 3 form