Yang-Mills in 2 dimensions for U(N) and its large-N limit

Ambar N. Sengupta

Louisiana State University

Classical and Random Dynamics in Mathematical Physics CoLab Workshop in Austin, TX, March/April 2010

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Yang-Mills: general background

Quantum Yang-Mills: Functional Integrals

Quantum Yang-Mills on  $\mathbb{R}^2$ 

Loop Expectation Values for U(N)

Stochastic Curvature in Quantum Yang-Mills

Freeness

Challenges

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ● ●

*Gauge fields* mediate the interaction between fundamental constituents.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

*Gauge fields* mediate the interaction between fundamental constituents. The most familiar gauge field is the *electromagnetic field*.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

*Gauge fields* mediate the interaction between fundamental constituents.

The most familiar gauge field is the *electromagnetic field*. The EM field is described by a *potential* which is a 1-form *A* on four-dimensional spacetime *M*.

(ロ) (同) (三) (三) (三) (三) (○) (○)

*Gauge fields* mediate the interaction between fundamental constituents.

The most familiar gauge field is the *electromagnetic field*. The EM field is described by a *potential* which is a 1-form *A* on four-dimensional spacetime *M*.

It acts on a point charge e with the force

force =  $ei_v F$ 

where v is the velocity of the charge and

$$F = -dA$$

(ロ) (同) (三) (三) (三) (三) (○) (○)

describes the strength of the electromagnetic field.

### Non-abelian gauge theory

Interaction between quarks is governed by a 1-form potential field A, buts values are skew-hermitian  $3 \times 3$  matrices. The field strength is

$${\sf F}^{\sf A}={\it d}{\sf A}+{\it A}\wedge{\it A}$$

Classical field configurations are extrema of the Yang-Mills action

$$S_{
m YM}(A) = rac{1}{2g^2} \int_M \langle F^A, F^A 
angle \, d{
m vol}$$

where g is a constant of physical significance, and integration is with respect to a volume measure on M.

Non-abelian gauge theory: quantum functional integral

Quantizing the gauge field itself requires (in one approach) using a *functional integral* measure

$$rac{1}{Z_g}e^{-S_{\mathrm{YM}}(A)}DA$$

and one wants to compute integrals of the form

$$\frac{1}{Z_g}\int_{\mathcal{A}}f(A)e^{-S_{\rm YM}(A)}DA$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

for functions f of interest on the infinite-dimensional space A.

Non-abelian gauge theory: quantum functional integral

Quantizing the gauge field itself requires (in one approach) using a *functional integral* measure

$$rac{1}{Z_g}e^{-S_{
m YM}(A)}DA$$

and one wants to compute integrals of the form

$$\frac{1}{Z_g}\int_{\mathcal{A}}f(A)e^{-S_{\rm YM}(A)}DA$$

for functions f of interest on the infinite-dimensional space A. Typical functions of interest are products of Wilson loop variables.

### Simplifying the quartic

Now

$$S_{\mathrm{YM}}(A) \simeq \| dA + A \wedge A \|^2$$

which is quartic in A, and so

$$\frac{1}{Z_g}e^{-S_{\rm YM}(A)}DA$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

is very difficult.

### Simplifying the quartic

Now

$$S_{\mathrm{YM}}(A) \simeq \| dA + A \wedge A \|^2$$

which is quartic in A, and so

$$rac{1}{Z_g}e^{-S_{\mathrm{YM}}(A)}DA$$

is very difficult.

Fortunately, we work only with A quotiented by a group  $G_o$  of symmetries (gauge transformations)

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のQ@

### Simplifying the quartic

Now

$$S_{\mathrm{YM}}(A) \simeq \| dA + A \wedge A \|^2$$

which is quartic in A, and so

$$rac{1}{Z_g}e^{-S_{\mathrm{YM}}(A)}DA$$

is very difficult.

Fortunately, we work only with A quotiented by a group  $G_o$  of symmetries (gauge transformations)

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

and this leads to a simplification in two dimensions.

### YM on $\mathbb{R}^2$ is Gaussian

On the plane  $\mathbb{R}^2$  a dramatic simplification occurs:

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

### YM on $\mathbb{R}^2$ is Gaussian

On the plane  $\mathbb{R}^2$  a dramatic simplification occurs: the space  $\mathcal{A}/\mathcal{G}_o$  can be identified with the the subspace of all connections

$$A = A_x dx + A_y dy$$

for which  $A_{y}$  is 0.



### YM on $\mathbb{R}^2$ is Gaussian

On the plane  $\mathbb{R}^2$  a dramatic simplification occurs: the space  $\mathcal{A}/\mathcal{G}_o$  can be identified with the the subspace of all connections

$$A = A_x dx + A_y dy$$

for which  $A_y$  is 0. Then

$$F^{A} = dA + \underbrace{A \wedge A}_{0} = dA = - \underbrace{\partial_{y}A_{x}}_{f^{A}} dx \wedge dy$$

(日) (日) (日) (日) (日) (日) (日)

This makes out functional integral measure have a very convenient appearance:

$$\frac{1}{Z_g} e^{-\frac{1}{2g^2} \|f\|_{L^2}^2} Df$$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ─ □ ─ の < @

### Gaussian measure in infinite dimensions

There is no useful form of Lebesgue measure in infinite dimensions.

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ─ □ ─ の < @

### Gaussian measure in infinite dimensions

There is no useful form of Lebesgue measure in infinite dimensions.

Gaussian measure in infinite dimensions makes sense and is extremely useful.

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のQ@

There is no useful form of Lebesgue measure in infinite dimensions.

Gaussian measure in infinite dimensions makes sense and is extremely useful.

Briefly, you take  $\mathbb{R}$  with Gaussian measure  $(2\pi)^{-1/2}e^{-x^2/2}dx$ and take an infinite product to obtain a probability measure on  $\mathbb{R}^{\{1,2,3,\ldots\}}$ .

(ロ) (同) (三) (三) (三) (三) (○) (○)



To summarize, the Yang-Mills measure for gauge theory on  $\mathbb{R}^2$  is rigorously meaningful and is Gaussian measure on the Hilbert space of functions

$$f:\mathbb{R}^2\to L(G)$$

Technically it lives on a Hilbert-Schmidt completion of  $L^2(\mathbb{R}^2) \otimes \text{Lie}(G)$ . Note that the original connection form *A* is now a very rough object obtained by 'integrating' *f*.

(ロ) (同) (三) (三) (三) (三) (○) (○)

#### **Stochastic Geometry**

Now consider a path

$$c: [0,1] \rightarrow \mathbb{R}^2: t \mapsto (t, y(t))$$

If A is a smooth connection on  $\mathbb{R}^2$ , parallel-transport along the path c is given by a path

$$[0,1] \rightarrow G: t \mapsto G: t \mapsto g_t$$

satisfying the differential equation

$$dg_t = -A(c'(t))g_t dt$$

Now that *A* is stochastic, this can be reinterpreted as a Stratonovich *stochastic differential equation* (idea of L. Gross).

### Holonomy and Wilson Loop Variables

If *A* is a connection and  $c : [0, 1] \rightarrow M$  a smooth loop, then  $g_1 \in G$  is called the *holonomy* of *A* around *c*:

$$h_c(A) \stackrel{\mathrm{def}}{=} g_1$$

#### Working with matrix groups G, we can form the trace

 $\operatorname{Tr}(h_{c}(A))$ 

which is a *Wilson loop variable*, as a function of the connection *A*.

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

### U(N) and heat kernel

We work with the unitary group

 $U(N) = \{N \times N \text{ complex matrices } A \text{ with } A^*A = I\}$ 

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ─ □ ─ の < @

### U(N) and heat kernel

We work with the unitary group

 $U(N) = \{N \times N \text{ complex matrices } A \text{ with } A^*A = I\}$ 

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ─ □ ─ の < @

 $Q_t(x)$  is the *heat kernel* on the group U(N).

### U(N) and heat kernel

We work with the unitary group

 $U(N) = \{N \times N \text{ complex matrices } A \text{ with } A^*A = I\}$ 

 $Q_t(x)$  is the *heat kernel* on the group U(N). It solves

$$\frac{\partial Q_t(x)}{\partial t} = \frac{1}{2} \Delta Q_t(x)$$

with initial condition

$$\lim_{t\downarrow 0}\int_{U(N)}f(x)Q_t(x)\,dx=f(I)$$

for every bounded continuous function f on U(N); and dx is unit-mass Haar on U(N).

### Stochastic Holonomy

In quantum YM on the plane, each piecewise smooth simple closed loop *c* in  $\mathbb{R}^2$  is associated with a *random variable*  $h_c$  with values in U(N).



### Loop expectation values notation

For a nice loop c, and a bounded measurable function f on U(N) we have the expectation value

$$\mathbb{E}_{N}\left[f(h_{c})\right]$$

We shall also write this as

 $\langle f(h_c) \rangle_N$ 

or simply as

 $\langle f(h_c) \rangle$ 

(日) (日) (日) (日) (日) (日) (日)

Conditions:

$$\langle f(h_c) \rangle = \int_{U(N)} f(x) Q_{g^2 S}(x) \, dx$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

for every bounded measurable function f on U(N)

Conditions:

$$\langle f(h_c) \rangle = \int_{U(N)} f(x) Q_{g^2 S}(x) \, dx$$

for every bounded measurable function f on U(N)

▶ if c<sub>1</sub>,..., c<sub>m</sub> are loops with disjoint interiors then h<sub>c1</sub>,..., h<sub>cm</sub> are *independent*,

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Conditions:

$$\langle f(h_c) \rangle = \int_{U(N)} f(x) Q_{g^2 S}(x) \, dx$$

for every bounded measurable function f on U(N)

▶ if c<sub>1</sub>,..., c<sub>m</sub> are loops with disjoint interiors then h<sub>c1</sub>,..., h<sub>cm</sub> are *independent*, i.e.,

$$\langle \prod_{j=1}^{m} f_j(h_{c_j}) \rangle = \prod_{j=1}^{m} \langle f_j(h_{c_j}) \rangle \rangle$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

for all bounded measurable  $f_1, ..., f_m$  on U(N).

Conditions:

$$\langle f(h_c) \rangle = \int_{U(N)} f(x) Q_{g^2 S}(x) \, dx$$

for every bounded measurable function f on U(N)

▶ if c<sub>1</sub>,..., c<sub>m</sub> are loops with disjoint interiors then h<sub>c1</sub>,..., h<sub>cm</sub> are *independent*, i.e.,

$$\langle \prod_{j=1}^{m} f_j(h_{c_j}) \rangle = \prod_{j=1}^{m} \langle f_j(h_{c_j}) \rangle \rangle$$

A D F A 同 F A E F A E F A Q A

for all bounded measurable  $f_1, ..., f_m$  on U(N).

(L. Gross, C. King. A.S.; Driver 1989)

Let

$$E_1, \dots, E_D \tag{1}$$

be an orthonormal basis of the space of  $N \times N$  hermitian matrices:

$$Tr(E_a E_b) = \delta_{ab}, \tag{2}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

where  $\delta_{ab}$  is 1 if a = b, and 0 otherwise.

Let

$$E_1, \dots, E_D \tag{1}$$

be an orthonormal basis of the space of  $N \times N$  hermitian matrices:

$$Tr(E_a E_b) = \delta_{ab}, \tag{2}$$

where  $\delta_{ab}$  is 1 if a = b, and 0 otherwise. The Laplacian is given by

$$\Delta = \sum_{a=1}^{D} \partial_{(iE_a)}^2, \tag{3}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Let

$$E_1, \dots, E_D \tag{1}$$

be an orthonormal basis of the space of  $N \times N$  hermitian matrices:

$$Tr(E_a E_b) = \delta_{ab}, \qquad (2)$$

where  $\delta_{ab}$  is 1 if a = b, and 0 otherwise. The Laplacian is given by

$$\Delta = \sum_{a=1}^{D} \partial_{(iE_a)}^2, \tag{3}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

and so,

$$\Delta \mathrm{Tr}_{N}(x) = \sum_{a=1}^{D} \partial_{iE_{a}} \mathrm{Tr}_{N}(xiE_{a})$$

Let

$$E_1, \dots, E_D \tag{1}$$

be an orthonormal basis of the space of  $N \times N$  hermitian matrices:

$$Tr(E_a E_b) = \delta_{ab}, \tag{2}$$

where  $\delta_{ab}$  is 1 if a = b, and 0 otherwise. The Laplacian is given by

$$\Delta = \sum_{a=1}^{D} \partial_{(iE_a)}^2, \tag{3}$$

and so,

$$\Delta \mathrm{Tr}_{N}(x) = \sum_{a=1}^{D} \partial_{iE_{a}} \mathrm{Tr}_{N}(xiE_{a}) = -\sum_{a=1}^{D} \mathrm{Tr}_{N}(xE_{a}^{2})$$

◆□▶ ◆□▶ ◆目▶ ◆目▶ 目 のへぐ

Let

$$E_1, \dots, E_D \tag{1}$$

be an orthonormal basis of the space of  $N \times N$  hermitian matrices:

$$Tr(E_a E_b) = \delta_{ab}, \qquad (2)$$

where  $\delta_{ab}$  is 1 if a = b, and 0 otherwise. The Laplacian is given by

$$\Delta = \sum_{a=1}^{D} \partial_{(iE_a)}^2, \tag{3}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

and so,

$$\Delta \operatorname{Tr}_{N}(x) = \sum_{a=1}^{D} \partial_{iE_{a}} \operatorname{Tr}_{N}(xiE_{a}) = -\sum_{a=1}^{D} \operatorname{Tr}_{N}(xE_{a}^{2}) = -N\operatorname{Tr}_{N}(x).$$
(4)
# The normalized trace

We will work with the normalized trace:

$$\mathrm{Tr}_N = \frac{1}{N}\mathrm{Tr}$$

Then

$$\operatorname{Tr}_{N}(I) = 1$$

Recall

$$\langle \mathrm{Tr}_N h_c \rangle = \int_{U(N)} \mathrm{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Recall

$$\langle \mathrm{Tr}_N h_c \rangle = \int_{U(N)} \mathrm{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

So

$$\frac{\partial \langle \mathrm{Tr}_N h_c \rangle}{\partial S} = \int_{U(N)} \mathrm{Tr}_N(x) \frac{\partial \mathcal{Q}_{g^2 S}(x)}{\partial S} \, dx$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Recall

$$\langle \mathrm{Tr}_N h_c \rangle = \int_{U(N)} \mathrm{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

So

$$\frac{\partial \langle \mathrm{Tr}_N h_c \rangle}{\partial S} = \int_{U(N)} \mathrm{Tr}_N(x) \frac{\partial Q_{g^2 S}(x)}{\partial S} \, dx$$

Using the heat kernel property:

$$\frac{\partial \langle \operatorname{Tr}_{N} h_{c} \rangle}{\partial S} = \frac{g^{2}}{2} \int \operatorname{Tr}_{N}(x) \Delta_{x} Q_{g^{2}S}(x) \, dx$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Recall

$$\langle \mathrm{Tr}_N h_c \rangle = \int_{U(N)} \mathrm{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

So

$$\frac{\partial \langle \mathrm{Tr}_N h_c \rangle}{\partial S} = \int_{U(N)} \mathrm{Tr}_N(x) \frac{\partial Q_{g^2 S}(x)}{\partial S} \, dx$$

Using the heat kernel property:

$$\frac{\partial \langle \operatorname{Tr}_N h_c \rangle}{\partial S} = \frac{g^2}{2} \int \operatorname{Tr}_N(x) \Delta_x Q_{g^2 S}(x) \, dx$$

Integrating by parts:

$$\frac{\partial \langle \operatorname{Tr}_N h_c \rangle}{\partial S} = \frac{g^2}{2} \int \Delta_x \operatorname{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

#### One-loop expectation value differential equation

$$\frac{\partial \langle \mathrm{Tr}_N h_c \rangle}{\partial S} = \frac{g^2}{2} \int \underbrace{\Delta_x \mathrm{Tr}_N(x)}_{-N\mathrm{Tr}_N(x)} Q_{g^2 S}(x) \, dx$$

Writing  $\tilde{g}^2 = g^2 N$ , we have

$$\frac{\partial \langle \mathrm{Tr}_N h_c \rangle}{\partial S} = -\frac{\tilde{g}^2}{2} \langle \mathrm{Tr}_N h(C) \rangle$$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ● □ ● ● ● ●

Recall

$$\langle \mathrm{Tr}_N h_c \rangle = \int_{U(N)} \mathrm{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

Recall

$$\langle \mathrm{Tr}_N h_c \rangle = \int_{U(N)} \mathrm{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ─ □ ─ の < @

Clearly,  $\langle \text{Tr}_N h_c \rangle$  equals 1 when S = 0.

Recall

$$\langle \mathrm{Tr}_N h_c \rangle = \int_{U(N)} \mathrm{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

Clearly,  $\langle \text{Tr}_N h_c \rangle$  equals 1 when S = 0. Also, the loop expectation value solves the differential equation

$$rac{\partial \langle {
m Tr}_N h_c 
angle}{\partial {\cal S}} = -rac{ ilde{g}^2}{2} \langle {
m Tr}_N h_c 
angle$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Recall

$$\langle \mathrm{Tr}_N h_c \rangle = \int_{U(N)} \mathrm{Tr}_N(x) Q_{g^2 S}(x) \, dx$$

Clearly,  $\langle Tr_N h_c \rangle$  equals 1 when S = 0. Also, the loop expectation value solves the differential equation

$$rac{\partial \langle {
m Tr}_N h_c 
angle}{\partial {\cal S}} = -rac{ ilde{g}^2}{2} \langle {
m Tr}_N h_c 
angle$$

Hence

$$\langle \mathrm{Tr}_{N}h_{c}
angle = e^{-\tilde{g}^{2}S/2}.$$
 (5)

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

## Reminder: the simple loop c



 $h_c$  is a U(N)-valued random variable, and

$$\langle \mathrm{Tr}_{N}h_{c}\rangle = e^{-\tilde{g}^{2}S/2}.$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

#### More moments

Next consider

$$W_N(c)_{\underline{k}} = \langle \mathrm{Tr}_N h_c^{k_1} \cdots \mathrm{Tr}_N h_c^{k_n} \rangle$$
(6)

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

for fixed  $k = |\underline{k}|$ , forming the components of a giant vector vector

 $\overrightarrow{W_N(c)}$ 

in the vector space

$$V_k = \mathbb{C}^{\{\underline{k}: |\underline{k}| = k\}}$$

#### Moment differential equation

#### Theorem (F. Xu (1997); A.S. (2007))

If S is the area enclosed by the simple loop c then

$$\frac{\partial W_{N}(c)}{\partial S} = -\frac{\tilde{g}^{2}}{2} \left[ k \mathrm{I} + \mathrm{II} + \frac{2}{N^{2}} \mathrm{III} \right] W_{N}(c).$$
(7)

Hence

$$\widetilde{W_N(c)} = e^{-\frac{\tilde{g}^2 S}{2}(kI + II + \frac{2}{N^2}III)}\mathbf{1},$$
(8)

where **1** is the vector in  $V_k$  with all entries equal to 1, and II and III are linear operators (matrices).

I, II, and III

$$\mathbf{I}f = f \tag{9}$$

#### and

$$IIf = \sum_{j=1}^{r} II_j f,$$
 (10)

#### where

$$(II_{j}f)_{\underline{k}} = k_{j} \sum_{s=1}^{k_{j}-1} f_{(k_{1},...,k_{j},s,k_{j}-s,...,k_{r})}, \qquad (11)$$

and

$$(\mathrm{III}f)_{\underline{k}} = \sum_{1 \le l < m \le r} k_l k_m f_{(k_1, \dots, k_l, \dots, k_m, \dots, k_r, k_l + k_m)}$$
(12)

# The method of proof is a generalization of the method used for $\langle {\rm Tr} h_{\rm C} \rangle.$

The method of proof is a generalization of the method used for  $\langle {\rm Tr} h_{\rm C} \rangle.$ 

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

T. Lévy (2008) provided a more insightful proof, along with many other related results, using Schur-Weyl duality of representations of  $S_n$  and U(N).

# Large-N limit

From

$$W_N(c) \stackrel{\mathrm{def}}{=} \langle \mathrm{Tr}_N h_c 
angle = e^{-\tilde{g}^2 |S|/2}$$

we have

$$W_{\infty}(c) \stackrel{\mathrm{def}}{=} \lim_{N \to \infty} W_N(c) = e^{-\tilde{g}^2 |S|/2}$$

exists.

# Large-N limit

From

$$W_N(c) \stackrel{\mathrm{def}}{=} \langle \mathrm{Tr}_N h_c 
angle = e^{- ilde{g}^2 |S|/2}$$

we have

$$W_{\infty}(c) \stackrel{\mathrm{def}}{=} \lim_{N o \infty} W_N(c) = e^{- ilde{g}^2 |S|/2}$$

exists.

Indeed,

$$\overrightarrow{W_{\infty}(c)} = \lim_{N o \infty} \overrightarrow{W_N(c)}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

exists, on consulting the theorem mentioned before.

Remarkably the following factorization occurs:

$$\lim_{N \to \infty} \left\langle \prod_{j=1}^{r} \operatorname{Tr}_{N}(h_{c}^{k_{j}}) \right\rangle = \prod_{j=1}^{r} \lim_{N \to \infty} \left\langle \operatorname{Tr}_{N}(h_{c}^{k_{j}}) \right\rangle.$$
(13)

As a special case, for  $k \in \{1, 2, ...\}$ ,

$$W_{\infty}(c^k) = e^{-k\frac{\tilde{g}^2}{2}S} P_k(\tilde{g}^2 S), \qquad (14)$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

where  $P_k(x)$  is an associated Laguerre polynomial of degree k - 1.

#### Two loops in one

Inner loop  $c_1$  encloses area  $S_1$ , and between  $c_1$  and the outer loop  $c_2$  lies area  $S_2$ .



#### Then

$$W_N(c_1c_2) = e^{-\frac{\tilde{g}^2}{2}(S_2+2S_1)} \left(\cosh(\tilde{g}^2S_1/N) - N\sinh(\tilde{g}^2S_1/N)\right)$$

◆□▶ ◆□▶ ◆□▶ ◆□▶ ● ● ● ●

I. M. Singer proposed that there is a 'universal bundle' over  $\mathbb{R}^2$ , and for each loop *c* in  $\mathbb{R}^2$  there is a unitary operator  $U_c$  on an infinite-dimensional Hilbert space and

$$W_{\infty}(c) = \operatorname{Tr}_{\infty} U_{c},$$

where  ${\rm Tr}_\infty$  is a certain trace functional, and similar results hold for multiple loops and higher moments.

(日) (日) (日) (日) (日) (日) (日)

#### Stochastic Curvature

In quantum Yang-Mills on  $\mathbb{R}^2$  to each subset  $\mathcal{S} \subset \mathbb{R}^2$  of finite area is associated a random matrix

 $F_N(S) \in \mathcal{H}_N$ 

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

where  $\mathcal{H}_N$  is the vector space of  $N \times N$  hermitian matrices.

#### Stochastic Curvature

In quantum Yang-Mills on  $\mathbb{R}^2$  to each subset  $\mathcal{S}\subset\mathbb{R}^2$  of finite area is associated a random matrix

 $F_N(S) \in \mathcal{H}_N$ 

where  $\mathcal{H}_N$  is the vector space of  $N \times N$  hermitian matrices. Informally,

$$iF_N(S) = \int_S \text{curvature} \in u(N) = i\mathcal{H}_N$$

(ロ) (同) (三) (三) (三) (○) (○)

# Matrix-valued White Noise

More generally,  $f \in L^2_{real}(\mathbb{R}^2)$ , a random  $N \times N$  matrix

 $F_N(f)$ 

(ロ) (同) (三) (三) (三) (○) (○)

satisfying the following conditions:

(i)  $F_N(f)$  is a random hermitian matrix;

# Matrix-valued White Noise

More generally,  $f \in L^2_{real}(\mathbb{R}^2)$ , a random  $N \times N$  matrix

 $F_N(f)$ 

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

satisfying the following conditions:

(i)  $F_N(f)$  is a random hermitian matrix;

(ii)  $F_N(f)$  depends linearly on f;

# Matrix-valued White Noise

More generally,  $f \in L^2_{real}(\mathbb{R}^2)$ , a random  $N \times N$  matrix

 $F_N(f)$ 

satisfying the following conditions:

- (i)  $F_N(f)$  is a random hermitian matrix;
- (ii)  $F_N(f)$  depends linearly on f;
- (iii) for  $f \neq 0$ , the random variable  $F_N(f)$  on  $\mathcal{H}_N$  has density proportional to

$$e^{-N\frac{\operatorname{Tr}(T^2)}{2\|f\|^2}}$$
 (15)

with *T* running over  $\mathcal{H}_N$ , the space of  $N \times N$  Hermitian matrices.

# Holonomy and Curvature

Given a curvature field  $F_N$ , holonomies  $h_c$  can be calculated by means of stochastic differential equations which mirror the equations of parallel-transport in differential geometry.

(ロ) (同) (三) (三) (三) (○) (○)

# Algebraic Probability Space

#### An algebraic probability 'measure' on ${\mathcal A}$ is a linear map

$$\phi: \mathcal{A} \to \mathbb{C}$$

satisfying

$$\phi(1) = 1$$

and

$$\phi(aa^*) \ge 0$$
 for all  $a \in \mathcal{A}$ .

We will call A, equipped with  $\phi$ , an *algebraic probability space*.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Take A to be the algebra of all  $N \times N$  complex matrices, with the involution being the adjoint:

$$A \mapsto A^*$$

and the non-commutative probability measure being given by

$$\phi(A) = \operatorname{tr}_N(A) \stackrel{\text{def}}{=} \frac{1}{N} \operatorname{tr}(A)$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

#### Random Matrix Example

Take A to be the algebra of all  $N \times N$  matrices whose entries are complex-valued *random variables* on some probability space, with the involution being the adjoint, and the non-commutative probability measure being given by

 $\phi(T) = \mathbb{E}[\operatorname{tr}_N(T)]$ 

(ロ) (同) (三) (三) (三) (○) (○)

#### Random Matrix Example

Take A to be the algebra of all  $N \times N$  matrices whose entries are complex-valued *random variables* on some probability space, with the involution being the adjoint, and the non-commutative probability measure being given by

$$\phi(T) = \mathbb{E}[\operatorname{tr}_{N}(T)]$$

A special case of interest is

$$T = \begin{bmatrix} T_{11} & T_{12} & \cdots & T_{1N} \\ \vdots & \vdots & \vdots & \vdots \\ T_{N1} & T_{N2} & \cdots & T_{NN} \end{bmatrix}$$

where

$$T_{ab} = S_{ab} + iA_{ab}$$

and the  $S_{ab}$ ,  $A_{cd}$  are jointly Gaussian variables.

Wigner's celebrated semi-circular law implies

$$\lim_{N \to \infty} \phi\left(F_N(f)^{2p}\right) = \|f\|^{2p} \frac{1}{p+1} \binom{2p}{p} \tag{16}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Thus

$$F_{\infty}(f) \stackrel{\text{def}}{=} \lim_{N \to \infty} F_N(f)$$

is a *semi-circular element* in a suitable probability algebra.

Consider subalgebras  $A_1, ..., A_N$ , all closed under \*. These are said to be *free* relative to each other if

$$\phi(a_1....a_M)=0$$

for any  $a_1, ..., a_M \in A$ , each with  $\phi(a_j) = 0$ , and *consecutive*  $a_j$  belong to distinct  $A_j$ .

▲□▶▲□▶▲□▶▲□▶ □ のQ@

# Applying Vociulescu's theorem to Noise

Returning to the orthogonal vectors  $f_1, ..., f_m \in L^2(\mathbb{R}^2)$ , and the corresponding independent Gaussian hermitian matrices  $F_N(f_j)$ , a fundamental result of Voiculescu implies:

$$(F_N(f_1),...,F_N(f_m)) \stackrel{\mathrm{d}}{\rightarrow} (f_1',...,f_m')$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

# Applying Vociulescu's theorem to Noise

Returning to the orthogonal vectors  $f_1, ..., f_m \in L^2(\mathbb{R}^2)$ , and the corresponding independent Gaussian hermitian matrices  $F_N(f_i)$ , a fundamental result of Voiculescu implies:

$$(F_{\mathcal{N}}(f_1),...,F_{\mathcal{N}}(f_m)) \stackrel{\mathrm{d}}{\rightarrow} (f_1',...,f_m')$$

(日) (日) (日) (日) (日) (日) (日)

where  $f'_1, ..., f'_m$  are mutually free elements in some algebraic probability space,
# Applying Vociulescu's theorem to Noise

Returning to the orthogonal vectors  $f_1, ..., f_m \in L^2(\mathbb{R}^2)$ , and the corresponding independent Gaussian hermitian matrices  $F_N(f_i)$ , a fundamental result of Voiculescu implies:

$$(F_{\mathcal{N}}(f_1),...,F_{\mathcal{N}}(f_m)) \stackrel{\mathrm{d}}{\rightarrow} (f_1',...,f_m')$$

where  $f'_1, ..., f'_m$  are mutually free elements in some algebraic probability space, and

each  $f'_j$  is *semicircular* with radius  $2||f_j||$  (if  $f_j$  is 0 then  $f'_j$  is 0).

・ロト・日本・日本・日本・日本

### Free limit of the curvature

Intepreting the preceding result in the context of stochastic curvature shows:

#### Theorem

The stochastic curvature field  $F_N(\cdot)$  converges in distribution to a free white noise process on the plane.

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のQ@



 $F(1_A)$  and  $F(1_B)$  are free

Figure: Free noise

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

# **Objectives/Challenges**

 Develop the full free Yang-Mills theory: relate curvature and holonomy.

# **Objectives/Challenges**

 Develop the full free Yang-Mills theory: relate curvature and holonomy.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

• Establish Singer's theory in the free framework.

# **Objectives/Challenges**

- Develop the full free Yang-Mills theory: relate curvature and holonomy.
- Establish Singer's theory in the free framework.
- Connect to Rajeev's QHD Grassmanian phase space for large-N QCD

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Thank you! Obrigado!