

# The Turaev-Viro-Barratt-Westbury state sum

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# Outline

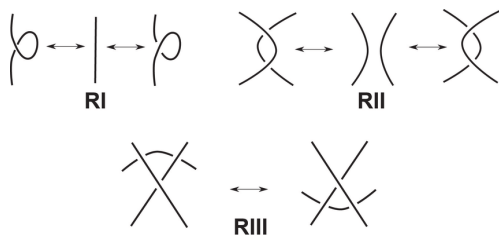
1. State sums: the what and the why
2. Monoidal categories, fusion categories, and spherical structures
3. Defining the TVBW model
4. (If time) A perspective on classifying 3d TFTs

# The state-sum perspective on defining TFTs

- ▶ Common paradigm: make a definition by introducing extra structure, then checking the definition is independent of that structure
- ▶ In low-dimensional topology, it's extremely common for this structure to be combinatorial
- ▶ Then, one proves that a finite set of “moves” relates all equivalent combinatorial structures on the underlying object

# Examples

- ▶ Knot invariants: choose a knot diagram (combinatorial structure), define an invariant of knot diagrams, and check that it is invariant under *Reidemeister moves*



- ▶ The Euler characteristic: choose a triangulation, count cells, and check that the answer does not depend on the triangulation

# State-sum models

- ▶ The idea of state-sum TFTs is to do this for topological field theories, by using the combinatorial data of a triangulation (or something like it) to define an invariant, then checking that it is independent of the choice of triangulation and that it satisfies gluing (so it is a TFT)
- ▶ Typically, one begins with input data of some kind of category  $\mathcal{C}$  with additional structure
  - ▶ Spherical fusion category: the TVBW model (3d TFT)
  - ▶ Ribbon fusion category: the Crane-Yetter model (4d TFT)
  - ▶ Many more (variants of Frobenius algebras for 2d oriented, spin,  $r$ -spin TFTs; Douglas-Reutter 4d state sum, ...)

# Coloring

- ▶ Generally the category  $\mathcal{C}$  has enough structure that we can make sense of simple objects (as in  $\mathcal{R}ep_G$ )
- ▶ A *coloring* of a triangulated manifold  $M$  is an assignment of a simple object of  $\mathcal{C}$  for every 1-simplex of  $M$
- ▶ The state-sum model fixes this and maybe additional data, then calculates the *weight* associated to each coloring, and the final invariant is a weighted sum using these weights
- ▶ To check invariance under change of triangulation, compute how it behaves under *Pachner moves*

# The Turaev-Viro-Barratt-Westbury model: basic facts

- ▶ Input data is something called a *spherical fusion category*  $\mathcal{C}$ , which axiomatizes the behavior that particles (“anyons”) in a 3d quantum system can have
- ▶ Turaev-Viro first defined this state sum in the special case where  $\mathcal{C}$  is the category of modules for the Drinfeld double of  $U_q(\mathfrak{sl}_2)$
- ▶ Then Barratt-Westbury generalized this to all spherical fusion categories
- ▶ Balsam-Kirillov made this model into a once-extended TFT, and studied its relationship with the *Levin-Wen model* in condensed-matter physics

# Defining a fusion category

- ▶ Begin with a  $\mathbb{C}$ -linear category (i.e. Hom-sets are complex vector spaces; composition is linear)
- ▶ Add a monoidal structure, where  $\otimes$  is bilinear on morphisms
- ▶ With this structure, we can define irreducible and indecomposable objects just as in representation theory
  - ▶ Irreducible (or simple): cannot be split as  $x \cong y \oplus z$  in a nontrivial way
  - ▶ Indecomposable: cannot be written as an extension in a nontrivial way



# Defining a fusion category

- ▶  $\mathcal{C}$  is *semisimple* if all objects are direct sums of simple ones
- ▶ Example:  $\mathcal{R}ep_G$ ,  $G$  finite, char 0. Nonexample:  $\mathcal{R}ep_G$ , characteristic dividing  $\#G$
- ▶ A *fusion category* is a semisimple  $\mathbb{C}$ -linear monoidal category with finitely many isomorphism classes of objects such that all objects have duals and the unit is simple

# Defining a spherical fusion category

- ▶ In  $\mathcal{Vect}_{\mathbb{C}}$ , we have a natural isomorphism  $\text{id} \Rightarrow (-)^{**}$
- ▶ In a general fusion category, we only have a canonical trivialization of the *quadruple* dual (Radford; see Douglas–Schommer-Pries–Snyder)
- ▶ A *pivotal structure* is a natural isomorphism  $\text{id} \Rightarrow (-)^{**}$

# Defining a spherical fusion category

- ▶ Pivotal is data, spherical is condition
- ▶ Specifically, ask that

$$d_+(x) := 1 \xrightarrow{c} x \otimes x^* \xrightarrow{\psi \otimes \text{id}} x^{**} \otimes x^* \xrightarrow{e} 1$$

$$d_-(x) := 1 \xrightarrow{c} x^* \otimes x^{**} \xrightarrow{\text{id} \otimes \psi^{-1}} x^* \otimes x \xrightarrow{e} 1$$

coincide

## Some notation

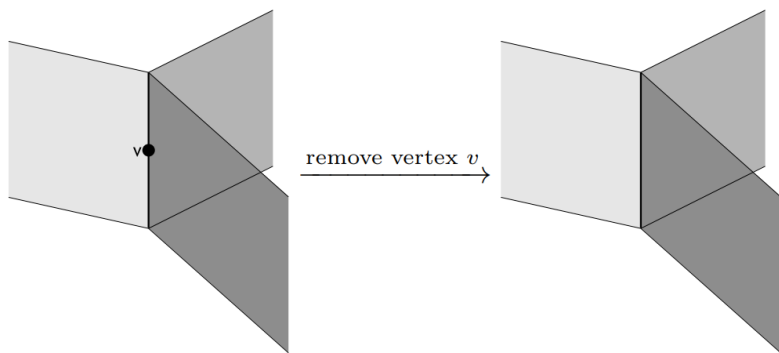
- ▶ Define  $\langle x_1, \dots, x_n \rangle := \text{Hom}_{\mathcal{C}}(1, x_1 \otimes \dots \otimes x_n)$  for  $x_1, \dots, x_n \in \mathcal{C}$
- ▶ The pivotal structure guarantees this “is invariant” under cyclic permutations (really: the pivotal structure provides a natural isomorphism between these functors)
- ▶  $S(\mathcal{C})$  denotes the finite set of isomorphism classes of simple objects
- ▶  $\dim(x) = d_+(x) = d_-(x)$  is the *dimension* of an object  $x$
- ▶ The *global dimension* is

$$D := \sqrt{\sum_{x \in S(\mathcal{C})} (\dim x)^2}$$

# Polytope decompositions

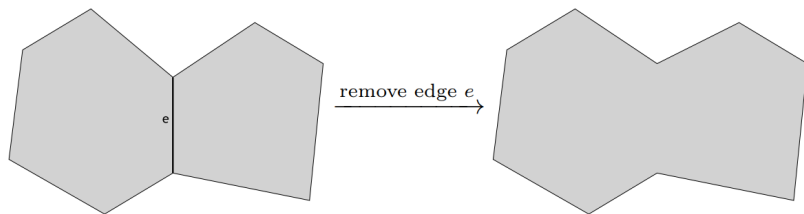
- ▶ This is a generalization of triangulations that allow for faces with more edges
- ▶ See Balsam-Kirillov
- ▶ We refer to a combinatorial manifold as a manifold with a polytope decomposition
- ▶ All combinatorial structures on the same underlying compact manifold are related by a finite series of Pachner moves (three in dimension 3)

# Pachner moves



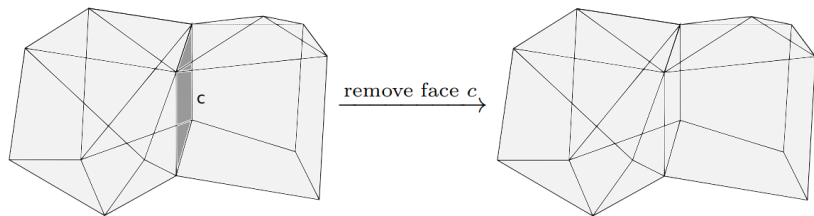
(Source: Balsam-Kirillov)

# Pachner moves



(Source: Balsam-Kirillov)

# Pachner moves



(Source: Balsam-Kirillov)



# Colorings

- ▶ To every *oriented* edge  $e$  of a combinatorial manifold  $M$ , assign a simple object of  $\mathcal{C}$
- ▶ Such that if you reverse the orientation of  $e$ , you get the dual object
- ▶ We will denote colorings  $\ell : \{\text{oriented edges}\} \rightarrow S(\mathcal{C})$

# Building the state space

- ▶ If  $f$  is an oriented 2-cell and  $\ell$  is a coloring, let

$$H(f, \ell) := \langle \ell(e_1), \dots, \ell(e_k) \rangle,$$

where  $e_1, \dots, e_k$  are the edges of  $f$  in cyclic order

- ▶ Now for a closed, oriented, combinatorial 2-manifold  $\Sigma$ , let  $H(\Sigma, \ell)$  be the direct sum of  $H(f, \ell)$  over all 2-cells  $f$  of  $\Sigma$ , and let  $H(\Sigma)$  be the direct sum of  $H(\Sigma, \ell)$  over all colorings  $\ell$
- ▶ Not yet the state space!

## Defining a vector for a 3-cell

- ▶ Next goal: given a 3-cell  $f$ , define a vector  $Z(f, \ell) \in H(\partial f, \ell)$
- ▶ Let  $\Pi$  be the polytope decomposition on  $\partial f = S^2$  induced from that on  $M$ , and let  $\Pi^\vee$  be the (Poincaré) dual polytope decomposition
- ▶ The labeling  $\ell|_\Pi$  of  $\Pi$  induces a labeling  $\ell^\vee$  of  $\Pi^\vee$ :  
 $\ell^\vee(e^\vee) = \ell(e)$  if  $e^\vee$  is given the “dual orientation”
- ▶ Precisely:  $e$  and  $e^\vee$  meet at a single point, and  $e^\vee$  should go from right to left from the point of view of  $e$

## Defining a vector for a 3-cell

- ▶ For every 2-cell  $C$  of  $\Pi$  (0-cell of  $\Pi^\vee$ ) choose  $\varphi_C \in H(C, \ell)^*$
- ▶ This defines a “string diagram” by removing a point of  $S^2$  and then using the edges in  $\Pi^\vee$  as strings joining the objects  $\varphi_C$  at the (dual) vertices
- ▶ This diagram can be evaluated: contract an edge to evaluate a vector and a covector
- ▶ The spherical structure is exactly what guarantees that it didn't matter how you removed a point to get from  $S^2$  to the plane

# Defining a vector for a 3-cell

- ▶ This procedure defines a function

$$\bigotimes_{C \in \Delta^2(\partial f)} H(C, \ell)^* = H(\partial f, \ell)^* \longrightarrow \mathbb{C},$$

meaning it is an element of  $H(f, \ell)^{**} = H(f, \ell)$

- ▶  $Z(f, \ell)$  is this element

# Defining the TVBW model on a 3-manifold

- For  $M$  a closed, oriented 3-manifold, we have a map

$$\bigotimes_{f \in \Delta^3(M)} H(\partial f, \ell) = H(\partial M, \ell) \otimes \bigotimes_{c \in \Delta^2(M \setminus \partial M)} \underbrace{H(c, \ell) \otimes H(c, \ell)^*}_{=H(-c, \ell)} \xrightarrow{\text{id}_{H(\partial M, \ell)} \otimes \otimes_c \text{ev}} H(\partial M, \ell),$$

where  $\text{ev}: V \otimes V^* \rightarrow \mathbb{C}$  is the evaluation map

- Apply this map to the vector

$$\bigotimes_{f \in \Delta^3(M)} Z(f, \ell) \in \bigotimes_{f \in \Delta^3(M)} H(\partial f, \ell)$$

and call the result  $Z(M, \ell)$

- Finally, sum this (with a normalization) over all weightings:

$$Z_{\mathcal{C}}(M) := \frac{1}{D^{2\nu(M)}} \sum_{\text{labelings } \ell} Z(M, \ell) \prod_{e \in \Delta^2(M)} \dim(\ell(e))^{n(e)} \in Z_{\mathcal{C}}(\partial M).$$

Here  $D$  is the dimension of  $\mathcal{C}$  as above;  $\nu$  is the number of interior edges of  $M$  plus  $1/2$  the number of boundary edges; and  $\nu(e)$  is 1 for interior edges and  $1/2$  for boundary edges

# Defining the state spaces

- ▶ Consider

$$Z_{\mathcal{C}}(\Sigma \times I) \in Z(\Sigma) \otimes Z(-\Sigma) = Z(\Sigma)^* \otimes Z(\Sigma) = \text{Hom}(Z(\Sigma), Z(\Sigma))$$

- ▶ This is a projection, and we define  $Z_{\mathcal{C}}(\Sigma)$  to be its kernel
- ▶ We had to triangulate the interval, but the answer turns out to not depend on this choice

## What we have so far

- ▶ We already have defined a vector space associated to a closed, oriented surface (with a triangulation – though it turns out to not depend on the triangulation)
- ▶ If  $M$  is a closed 3-manifold,  $Z_{\mathcal{C}}(M)$  is an element of  $Z_{\mathcal{C}}(\emptyset)$ , which is isomorphic to  $\mathbb{C}$  kind of vacuously. So we get a partition function
- ▶ More generally if  $M$  is an oriented bordism from  $\Sigma_0$  to  $\Sigma_1$ , it comes with an identification  $\partial M \cong -\Sigma_0 \amalg \Sigma_1$ , and therefore

$$Z_{\mathcal{C}}(M) \in Z_{\mathcal{C}}(\partial M) = Z_{\mathcal{C}}(\Sigma_0)^* \otimes Z_{\mathcal{C}}(\Sigma_1) = \text{Hom}(Z_{\mathcal{C}}(\Sigma_0), Z_{\mathcal{C}}(\Sigma_1)).$$

That is, this construction defines a map  $Z_{\mathcal{C}}(\Sigma_0) \rightarrow Z_{\mathcal{C}}(\Sigma_1)$ , as we wanted



# Many things yet left to check

- ▶ Does disjoint union map to tensor product? (Yes, and this isn't that hard.)
- ▶ Why are all of these invariant under the Pachner moves?
- ▶ Why does a cylinder act by the identity?
- ▶ Why does gluing of bordisms correspond to composition?

# Finite gauge theory

- ▶ There is a spherical fusion category structure on  $\mathcal{Vect}_G$ , the category of  $G$ -graded vector bundles
- ▶ Monoidal structure is convolution:

$$(V \otimes W)_g = \bigoplus_{h \in G} V_h \otimes W_{h^{-1}g}$$

- ▶ Upshot: this is a fusion category
- ▶ Use the standard pivotal structure on  $\mathcal{Vect}$  to define one on  $\mathcal{Vect}_G$ , giving a spherical structure
- ▶ The TVBW model for this is finite gauge theory (aka untwisted Dijkgraaf-Witten theory)

# Dijkgraaf-Witten theory

- ▶ Choose a cocycle  $\alpha \in Z^n(BG; \mathbb{C}^\times)$ , concretely a map  $\alpha: G \times G \times G \rightarrow \mathbb{C}^\times$
- ▶ Use  $\alpha$  to twist the associator

$$\alpha: (U_g \otimes V_h) \otimes W_k \Longrightarrow U_g \otimes (V_h \otimes W_k)$$

- ▶ Specifically, we have the standard associator coming from  $\mathcal{Vect}$ ; multiply it by  $\alpha(g, h, k) \in \mathbb{C}^\times$
- ▶ Cocycle implies this satisfies the pentagon identity; cohomologous cocycles define isomorphic theories: Dijkgraaf-Witten theory for  $[\alpha] \in H^n(BG; \mathbb{C}^\times)$

## Additional examples: quantum groups

- ▶ Given a semisimple Lie algebra  $\mathfrak{g}$  and  $q \in \mathbb{C}^\times$ , one can deform the universal enveloping algebra  $U(\mathfrak{g})$  to a “quantum group”  $U_q(\mathfrak{g})$
- ▶ For  $q$  a root of unity, it is possible to extract a spherical fusion category from the category of representations of  $U_q(\mathfrak{g})$
- ▶ Closely related to Chern-Simons theories for the simply connected group with Lie algebra  $\mathfrak{g}$  — not the same, but related

# Tambara-Yamagami TFTs

- ▶ Choose a finite abelian group  $A$ , a square root  $z$  of  $1/\#A$ , and a nondegenerate symmetric bilinear form  $\chi : A \times A \rightarrow \mathbb{C}^\times$ ; this data defines a spherical fusion category  $\mathcal{T}\mathcal{Y}(A, z, \chi)$  called a *Tambara-Yamagami category*
- ▶ Simple objects are indexed by elements of  $A$  plus an additional object  $m$
- ▶ Monoidal structure:  $a \otimes b = ab$  ( $a, b \in A$ ),  $a \otimes m = m \otimes a = m$ , and  $m \otimes m = \bigoplus_{a \in A} a$ . The unit is  $1 \in A$

# Tambara-Yamagami TFTs

- ▶ Morphisms are as in Schur's lemma: for simple objects,  $\text{Hom}(x,y) = \mathbb{C}$  if  $x \cong y$ , and 0 if otherwise
- ▶ Defining the associator:

$$\alpha(a, m, b) := \chi(a, b) \cdot \text{id}_m : m \rightarrow m$$

$$\alpha(m, a, m) := (\chi(a, x) \delta_{xy} \text{id}_x) : \bigoplus_{x \in A} x \rightarrow \bigoplus_{y \in A} y$$

$$\alpha(m, m, m) := z \chi(x, y)^{-1} \text{id}_m : \bigoplus_{x \in A} m \rightarrow \bigoplus_{y \in A} m$$

The remaining ones are all the identity