

# Compactness of Stable Minimal Surfaces

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# A Roadmap:

Want to prove the following theorem:

## Theorem

*Let  $U \subset \mathbb{R}^n$  be open with  $3 \leq n \leq 6$ . Suppose  $\Sigma_k \subset U$  is a sequence of stable minimal hypersurfaces with  $\text{Vol}(\Sigma_k) \leq a$ . Then there exists a subsequence converging to  $\Sigma$ , a stable minimal hypersurface in  $U$  (possibly with multiplicity).*

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- Instead of asking for some global convergence of these surfaces, we instead turn to local convergence, and show that these patch nicely together.
- To handle local convergence, we'll need to show our surfaces can (locally) be written as graphs of functions.
- Of course, you can do that for any smooth surface, what we're really need is a uniform way of doing this.
- Idea: Maybe if our surface is not curving too badly, we can get uniform graphicality.
- Since the second fundamental form  $A$  dictates curvature, we should establish bounds on  $|A|^2$ .

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# A Roadmap:

- Step 1: Fix a compact  $K \subset U$ . Given our sequence of stable minimal surfaces  $\Sigma_k \subset U$ , show that  $|A_k|^2$  are uniformly bounded on  $K$ .
- Step 2: Show that each  $\Sigma_k \cap K$  is uniformly graphical.
- Step 3: Transition to a local argument, use Arzela-Ascoli to find a limit  $C^{1,\alpha}$  function satisfying the minimal surface equation.
- Step 4: Establish global convergence. Show that intersecting graphs actually patch together nicely.

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## A Roadmap:

- We'll discuss the theorems involved in Steps 1 and 2. Our motto is “small curvature implies graphical”.

### Theorem

Let  $\Sigma \subset \mathbb{R}^n$  be a stable, minimal hypersurface with  $\partial\Sigma \subset \partial B_R(0)$ ,  $\text{Vol}(\Sigma \cap B_R(0)) \leq aR^{n-1}$  for some  $a > 0$ , and  $3 \leq n \leq 6$ . Then there exists some  $C(n, a)$  (independent of  $\Sigma$ !) such that

$$\sup_{\Sigma \cap B_R(0)} d(x, \partial B_R(0))^2 |A|^2(x) \leq C(n, a).$$

In particular, if  $0 \in \Sigma$  then

$$|A|^2(0) \leq \frac{C(n, a)}{R^2}.$$

## A Roadmap:

- We'll discuss the theorems involved in Steps 1 and 2. Our motto is “small curvature implies graphical”.

### Theorem (Small Curvature Implies Graphical)

Let  $\Sigma \subset \mathbb{R}^n$  be an immersed hypersurface with

$$16s^2 \sup_{\Sigma} |A|^2(x) \leq 1.$$

If  $x \in \Sigma$  and  $d(x, \partial\Sigma) \geq 2s$ , then there is a function  $u$  defined on  $B_s^T(x) := B_s(x) \cap T_x\Sigma$  such that  $B_s^\Sigma(x) \subset \text{Graph}(u) \subset B_{2s}^\Sigma(x)$ . Moreover,  $|\nabla u| \leq 1$  and  $\sqrt{2} |\text{Hess}(u)| \leq 1$ .

# Minimal Surfaces:

What is a minimal surface?

Let  $\Sigma^k \subset \mathbb{R}^n$  be a submanifold and  $F : \Sigma \times (-\epsilon, \epsilon) \rightarrow \mathbb{R}^n$  such that  $F = \text{Id}$  outside a compact set and  $F|_{\partial\Sigma} = \text{Id}$ . Then one can show the first variation of the volume satisfies

$$\delta \text{Vol}(\Sigma, F) = \left. \frac{d}{dt} \text{Vol}(F(\Sigma, t)) \right|_{t=0} = - \int_{\Sigma} \langle F_t, H \rangle.$$

## Definition

A submanifold  $\Sigma^k \subset \mathbb{R}^n$  is a minimal surface if for all such variations  $F$  we have  $\delta \text{Vol}(\Sigma, F) = 0$ . So,  $\Sigma$  is a critical point of the (area) functional  $\text{Vol}$ , defined by

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# The Monotonicity Formula:

## Theorem (The Coarea Formula)

If  $\Sigma$  is a manifold and  $h : \Sigma \rightarrow \mathbb{R}$  is a proper Lipschitz function on  $\Sigma$ , then for all  $f \in L^1_{loc}(\Sigma)$  and  $r \in \mathbb{R}$ ,

$$\int_{\{h \leq r\}} f |\nabla_{\Sigma} h| = \int_{-\infty}^r \int_{\{h=\tau\}} f \, d\tau.$$

## Theorem (The Monotonicity Formula)

Let  $\Sigma^k \subset \mathbb{R}^n$  be a minimal submanifold and  $x_0 \in \mathbb{R}^n$ . Then for all  $0 < s < t$  we have

$$\frac{\text{Vol}(\Sigma \cap B_t(x_0))}{t^k} - \frac{\text{Vol}(\Sigma \cap B_s(x_0))}{s^k} = \int_{\Sigma \cap B_t(x_0) \setminus \Sigma \cap B_s(x_0)} \frac{|(x - x_0)^N|^2}{|x - x_0|^{k+2}}.$$

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## Theorem (Generalized Monotonicity)

If  $\Sigma^k \subset \mathbb{R}^n$  is a minimal submanifold and  $f : \Sigma \rightarrow \mathbb{R}$  a function then

$$t^{-k} \int_{\Sigma \cap B_t} f - s^{-k} \int_{\Sigma \cap B_s} f = \int_{\Sigma \cap B_t \setminus \Sigma \cap B_s} f \frac{|x^N|^2}{|x|^{k+2}} + \frac{1}{2} \int_s^t \tau^{-k-1} \int_{\Sigma \cap B_\tau} (\tau^2 - |x|^2) \Delta_\Sigma f \, d\tau.$$

## Theorem (The Mean Value Inequality)

Let  $\Sigma^k \subset \mathbb{R}^n$  be a minimal submanifold,  $x_0 \in \Sigma$ , and  $s > 0$  with  $B_s(x_0) \cap \partial\Sigma = \emptyset$ . If  $f$  is nonnegative on  $\Sigma$  with  $\Delta_\Sigma f \geq -\lambda s^{-2} f$ , then

$$f(x_0) \leq \frac{e^{\lambda/2}}{\text{Vol}(\Sigma \cap B_s)} \int_{\Sigma \cap B_s(x_0)} f.$$

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## The Second Fundamental Form:

### Definition

Let  $\Sigma^k \subset \mathbb{R}^n$  be an embedded submanifold. The second fundamental form  $A$  is defined pointwise by  $A_x : T_x \Sigma \times T_x \Sigma \rightarrow \mathbb{R}^n$  where

$$A_x(X, Y) = (\nabla_X Y)^N.$$

### Remark

One way to write the mean curvature vector of  $\Sigma$  is as

$$H(x) = \sum_{i=1}^k A_x(E_i, E_i)$$

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### Theorem (Simon's inequality)

Let  $\Sigma \subset \mathbb{R}^n$  be a minimal hypersurface. Then,

$$\Delta_{\Sigma}|A|^2 \geq -2|A|^4 + 2 \left(1 + \frac{2}{n-1}\right) |\nabla_{\Sigma}|A||^2.$$

### Remark

Since the right-most term is nonnegative, if  $|A|^2 \leq 1$  then

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In particular, we can use the Mean Value Inequality to estimate  $|A|^2$ . In fact, since  $\Delta_{\Sigma} f^p \geq p f^{p-1} \Delta_{\Sigma} f$  for  $p > 1$  we get  $\Delta_{\Sigma}|A|^{2p} \geq -2p|A|^{2p}$ . So, we can estimate  $|A|^{2p}$  via the Mean Value Inequality.



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# Stable Minimal Surfaces:

## Definition

Let  $\Sigma \subset \mathbb{R}^n$  be an orientable hypersurface. Then for smooth functions  $\eta$  we define the stability operator  $L$  by

$$L\eta = \Delta_{\Sigma}\eta + |A|^2\eta.$$

## Theorem

*Let  $\Sigma^k \subset \mathbb{R}^n$  be an orientable, minimal submanifold. If  $F$  is a normal variation of  $\Sigma$  with compact support then*

$$\delta^2 \text{Vol}(\Sigma, F) = \left. \frac{d^2}{dt^2} \right|_{t=0} \text{Vol}(F(\Sigma, t)) = - \int_{\Sigma} \langle F_t, LF_t \rangle$$

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## Definition

We say that  $\Sigma$  is stable if for all compactly supported normal variations  $F$  which fix  $\partial\Sigma$  that  $\delta^2 \text{Vol}(\Sigma, F) \geq 0$ . In other words,  $\Sigma$  is a minimizer of the (area) functional.

## Theorem (Stability Inequality)

*Let  $\Sigma \subset \mathbb{R}^n$  be a stable, orientable, minimal hypersurface. Then for all Lipschitz functions  $\eta$  with compact support,*

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Is there an  $L^p$  analog of this?

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## Stable Minimal Surfaces:

Yes, due to Schoen-Simon-Yau! For certain  $p$  at least.

### Theorem ( $L^p$ Stability Inequality)

Let  $\Sigma \subset \mathbb{R}^n$  be a stable, orientable, minimal hypersurface. Then for all compactly supported nonnegative Lipschitz functions  $\phi$  and  $p \in [2, 2 + \sqrt{2/(n-1)}]$  we have

$$\int_{\Sigma} |A|^{2p} \phi^{2p} \leq C(n, p) \int_{\Sigma} |\nabla \phi|^{2p}.$$

## Summary:

Minimal surfaces are critical points of the area functional, and give us monotonicity of

$$\frac{\text{Vol}(\Sigma \cap B_t(x_0))}{t^k}$$

in  $t$ . Given a lower bound on the Laplacian of  $f$  in terms of  $f$ , the mean value inequality gives a pointwise bound in terms of an integral

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## Proof of Estimate:

We're now ready to prove our first estimate theorem

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Method: A proof by contradiction using a blowup argument.

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## Proof of Estimate:

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Suppose there does not exist such a  $C(n, a)$ . Then there exists a sequence of stable minimal hypersurfaces  $\Sigma_k$  such that

$$\sup_{\Sigma_k \cap B_R(0)} |A_k|^2 (R - |x|)^2 \geq k^2.$$

Now fix a  $k \in \mathbb{N}$  and choose  $p_k \in \Sigma_k \cap B_R(0)$  such that the sup is attained. If  $y \in \Sigma_k \cap B_R(0)$  then

$$|A_k(y)|^2 = \frac{|A_k(y)|^2 (R - |y|)^2}{(R - |y|)^2} \leq \frac{|A_k(p_k)|^2 (R - |p_k|)^2}{(R - |y|)^2}.$$

So, to control  $|A_k(y)|^2$  within  $B_R(0)$ , we need control on  $(R - |p_k|)/(R - |y|)$ .

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## Proof of Estimate:

### Proof Continued

Can't do this on all of  $B_R(0)$ , need to shrink to a smaller ball. Define  $\sigma_k$  by

$$\sigma_k = \frac{k}{2|A_k(p_k)|}.$$

We immediately have

$$\frac{k^2(R - |p_k|)^2}{4\sigma_k^2} = |A_k(p_k)|^2(R - |p_k|)^2 \geq k^2$$

This implies  $R - |p_k| \geq 2\sigma_k$ , and so  $B_{2\sigma_k}(p_k) \subset B_R(0)$ . Next, for  $y \in B_{\sigma_k}(p_k)$ ,

$$\frac{R - |y|}{R - |p_k|} \geq \frac{R - |p_k| - \sigma_k}{R - |p_k|} = 1 - \frac{\sigma_k}{R - |p_k|} \geq \frac{1}{2}.$$



## Proof of Estimate:

### Proof Continued

Can't do this on all of  $B_R(0)$ , need to shrink to a smaller ball. Define  $\sigma_k$  by

$$\sigma_k = \frac{k}{2|A_k(p_k)|}.$$

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# Proof of Estimate:

## Proof Continued

So, if  $y \in \Sigma_k \cap B_{\sigma_k}(p_k)$  then

$$|A_k(y)|^2 \leq \frac{|A_k(p_k)|^2 (R - |p_k|)^2}{(R - |y|)^2} \leq 4|A_k(p_k)|^2.$$

Thus,  $|A_k|^2$  on  $\Sigma_k \cap B_{\sigma_k}(p_k)$  is controlled by  $|A_k(p_k)|^2$ .

With this information, we can now begin our blowup argument.

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# Proof of Estimate:

## Proof Continued

Blowup Step 1: Define  $\mu_k : B_R(0) \rightarrow \mathbb{R}^n$  by  $\mu_k(x) = 2|A_k(p_k)|(x - p_k)$ . Let  $\tilde{\Sigma}_k = \mu_k(\Sigma_k \cap B_{\sigma_k}(p_k))$ . Recalling  $\sigma_k = k/(2|A_k(p_k)|)$ ,  $\mu_k$  maps  $B_{\sigma_k}(p_k)$  to  $B_k(0)$ .

Note that the second fundamental form scales by  $1/(2|A_k(p_k)|)$ . So, if  $\tilde{A}_k$  is the second fundamental form of  $\tilde{\Sigma}_k$  then for all  $y \in \tilde{\Sigma}_k$ ,

$$|\tilde{A}_k(y)|^2 = \frac{|A_k(\mu_k^{-1}(y))|^2}{4|A_k(p_k)|^2} \leq 1.$$

Importantly, the mean value inequality applies! Noting that  $|\tilde{A}_k(0)| = 1/2$ ,

$$\frac{1}{2^{2p}} = |\tilde{A}_k(0)|^{2p} \leq C(n) \int_{\tilde{\Sigma}_k \cap B_1(0)} |\tilde{A}_k|^{2p} \leq C(n) \int_{\tilde{\Sigma}_k \cap B_k(0)} |\tilde{A}_k|^{2p}.$$

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## Proof Continued

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# Proof of Estimate:

## Proof Continued

Blowup Step 2: Define a cutoff function  $\phi_k$  where  $\phi_k|_{B_k(0)} \equiv 1$ ,  $\phi_k|_{B_{2k}^c(0)} \equiv 0$ , and  $\phi_k$  decreases radially from  $k$  to  $2k$  (so  $|\nabla\phi_k| = 1/r$ ).

Applying our  $L^p$  stability inequality with this cutoff function and  $2p = 4 + \sqrt{7/5}$ ,

$$\begin{aligned} \int_{\tilde{\Sigma}_k \cap B_{2k}(0)} |\tilde{A}_k|^{2p} \phi_k^{2p} &\leq C(n) \int_{\tilde{\Sigma}_k \cap B_{2k}(0)} |\nabla\phi_k|^{2p} \\ &\leq C(n) k^{-4 - \sqrt{7/5}} \text{Vol}(\tilde{\Sigma}_k \cap B_{2k}(0)). \end{aligned}$$

# Proof of Estimate:

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# Proof of Estimate:

## Proof Continued

In total,

$$\begin{aligned} \frac{1}{2^{4+\sqrt{7/5}}} &\leq C(n) \int_{\tilde{\Sigma}_k \cap B_k(0)} |\tilde{A}_k|^{2p} \leq C(n) \int_{\tilde{\Sigma}_k \cap B_{2k}(0)} |\tilde{A}_k|^{2p} \phi_k^{2p} \\ &\leq C(n) k^{-4-\sqrt{7/5}} \text{Vol}(\tilde{\Sigma}_k \cap B_{2k}(0)) \end{aligned}$$

Blowup Step 3: Use volume bound to arrive at a contradiction.

## Proof of Estimate:

### Proof Continued.

Blowup Step 3: Use volume bound to arrive at a contradiction. Recall  $\text{Vol}(\Sigma_k \cap B_R(0)) \leq aR^{n-1}$  for some  $a > 0$ . Since the volume scales like  $n - 1$ , we get

$$\begin{aligned}\text{Vol}(\tilde{\Sigma}_k \cap B_{2k}(0)) &= (2|A_k(p_k)|)^{n-1} \text{Vol}(\Sigma_k \cap B_{2\sigma_k}(p_k)) \\ &= \frac{(2k)^{n-1} \text{Vol}(\Sigma_k \cap B_{2\sigma_k}(p_k))}{(2\sigma_k)^{n-1}} \\ &\leq \frac{(2k)^{n-1} \text{Vol}(\Sigma_k \cap B_R(0))}{R^{n-1}} \leq a(2k)^{n-1}\end{aligned}$$

Finally,

$$\frac{1}{2^{4+\sqrt{7/5}}} \leq C(n, a)k^{-4-\sqrt{7/5}+n-1}.$$

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