A knot K is an oriented circle in
$$S^3$$
.
We can view $S^3 = \partial B^4$ and study knots in 4D.
K is slice in B⁴ if K
bounds a smoothly embedded
disk in B⁴.



Nice case: K is <u>ribbon</u> if K bounds a slice disk D in B⁴ so hld is Morse with no maxima. (h=radial height) This is nice because we can project to S³ and get ribbon-immersed disk h (or vice versa)





Relative 4D Poincaré Onjecture: If V' is a homotopy 4-ball, then $V' \cong B'$.

Now view S= JV4, V a homotopy 4-ball. K^{cs3} is homotopy-slice if K bounds a disk smoothly embedded in some V.

What does <u>ribbon</u> say about <u>algebra</u>?





Def K is homotopy-ribbon if there exists a homotopy 4-ball V' and smooth disk DCV with DD=K and smooth our $2:\pi, (S^3 \setminus K) \xrightarrow{\text{surjection}} (V \setminus D)$

What does <u>ribbon</u> say about topology?) IF D ribbon, B'\u(D) admits handle decomposition with no 3-handles.

Def K is handle-ribbon if there exists a homotopy 4-ball V and smooth disk DCV with $(S^3, K) = \partial(V, D)$ so that V'(r(D)) admits a handle decomposition with no 3-handles.

Inclusions
{Ribbon 3
$$\leq$$
 {Handle-ribbon 3 \leq {Homotopy-B43 \leq {slice}}
in B4 (ribbon in B4) \leq {slice}
Slice-ribbon conjecture (Fox 1962) : \leq is =

Derivatives A derivative far a knot K is a g-component link L=Lu-iuLg on a genus-g Seifert surface F far K . [L;] independent i . [L;] independent i . [L;] independent i . [L;] independent i Finduces O-framing on L; V; Note: K has a derivative K is algebraically slice



Slice knots A <u>slice derivative</u> for K is a derivative L=L, U--- ULg that bounds UD² in B⁴. Fms a slice disk for K K has a \implies K is slice derivative R4





Conclude: If K has R-derivative, then K is handle-ribbon.

handle-ribbon, then 14 is $|\uparrow\rangle$ $V \setminus (D) = S_{o}(K) \times T$ V (2; 3; and 4-handles) L=attaching circles of 2-handles $\sim S_{0}^{3}(|K \cup L) = \# S^{2} \times S^{1}$





Say g(F) = |L| + n. If n=0, we're done. $\ln S^{3}(K \cup L) = \# S^{2} \times S', \text{ cap off } F' \text{ and}$ compress along L to get a genus -n surface Ê <07 glue disk to cap off JFI L <07 - compress

r cor F glue disk lt'n>0, then È is compressible along some curve C. Since [C] = o in H₁(Ê), Since C=unknot in So(KUL) [C] independent from [L:] in H, (F') ·C O-framed by F \cdot $k(C, L;) = O \forall :$ Set L:= LUC and continue inductively.

Related theorem of Casson-Gordon (1983) Say K is fibered: $S^3 \setminus (K) \cong F_x S^1$ Then K is homotopy-ribbon if and only if q extends to a handlebody.

(or For K <u>fibered</u>: K is homotopy-ribbon if and only if there exists a homotopy 4-ball V and smooth disk DCV s.t. • $(S^{3},K)=\partial(V,D)$ V\v(D) is a bundle of handlebodies over S' s' (Write "D is fibered")

PE E Write down presentation for n, ⇒ Start with K fibered, homtopy-ribbon. (G⇒ Pextends to q:H→H 2-handle Hx_qS' V=S*IU(O-framed 2-handle)UHXaS' along K×I D=K×IU(core of 2-handle)

Thm (M-Zupan) Kaknot. Then K is handle-ribbon if and only if there exists a circular Morse function f: S°(K)→S' 50 index-0 pts 2 n index-1 pts n index-2 pts extending to a 0 index-3 pts 1 v circular Marse Function f: W-> S's.t. · f has n interior critical points, all index-? • regular fibers of f are handlebodies, $\cdot \chi(\omega) = O$

(There is actually a stronger theorem in terms of) Morse 2-functions, but I didn't want to) introduce them. M-Zupan D: S'Morse function Casson - Gordon Fibration on 2 homotopyhandleribben 66 66 Some Singular fibers (index-2) Fibration in Interior

Pf (easy direction only) E Starting with f: U →5¹ S index-1 -genus biggest) le 66 £: 91 6 thich" thin thick 6 6 51 smallest-genus leaf "thin" 6 index-2

Whas no 3-handles!
Also #1-handles=#2-handles+1.

$$\Rightarrow H_{\star}(W; \mathbb{Z}) = H_{\star}(S'; \mathbb{Z})$$

Moreover $\pi_{i}(W) = \langle \chi(K) \rangle$
 $Moreover \pi_{i}(W) = \langle \chi(K) \rangle$
 Mor

(Not a proof) Hard direction (Really would prove via Morse 2-functions) K handle-ribbon rel boundary: J×I -handles V - v(D) = 34-hardle



• Started with $f_{i}:=f:f_{i}(0) \rightarrow S'$ Explicitly build f_t: h'(t) → S' so F(x) := f_{h(x)} (x): V(x(D) → S' is smooth h(x) to control {critical ptsof F3 ⊆ {(x,t) | f_t(x) not Morse3

