

LECTURE 14

02/20/12

11

MULTIPLICITY OF EIGENVALUES, DIAGONALIZABILITY (CONT'D):

TO RECAP:  $A \in M_{n,n}$  HAS DISTINCT EIGENVALUES  $\lambda_1, \dots, \lambda_r \in \mathbb{C}$ .

$$\begin{array}{ccc} (\lambda_1, E_{\lambda_1}), & \dots, & (\lambda_r, E_{\lambda_r}) \\ \begin{array}{c} (z-\lambda_1)^{m_1} \downarrow \\ m_1 \end{array} & \begin{array}{c} \downarrow \dim E_{\lambda_1} \\ M_1 \end{array} & \begin{array}{c} (z-\lambda_r)^{m_r} \downarrow \\ m_r \end{array} & \begin{array}{c} \downarrow \dim E_{\lambda_r} \\ M_r \end{array} \end{array}$$

- $m_i$  ALGEBRAIC MULTIPLICITY OF  $\lambda_i$
- $M_i$  GEOMETRIC MULTIPLICITY OF  $\lambda_i$ .

LAST TIME, WE SHOWED THAT

(i)  $1 \leq M_i \leq m_i$  FOR ALL  $i=1, \dots, r$

(ii)  $E_{\lambda_1}, \dots, E_{\lambda_r}$  ARE DISTINCT SUBSPACES IN THAT THEY ARE LINEARLY INDEP.

THESE IMMEDIATELY IMPLY:

THM. (DIAGONALIZABILITY)

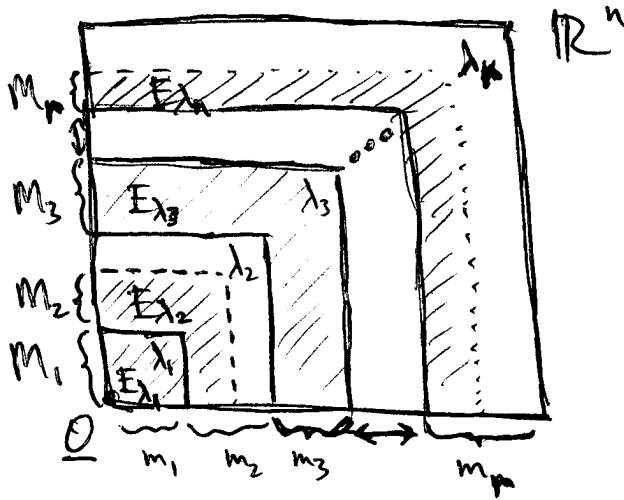
$A \in M_{n,n}$  DIAGONALIZABLE, I.E., CAN FIND  $n$  LINEARLY INDEP. EIGENVECTORS

( $A = P D P^{-1}$  FOR SOME  $D$  DIAGONAL)

$\iff M_i = m_i$  FOR ALL  $i=1, \dots, r$ .

• IN PARTICULAR, IF  $A$  HAS  $n$  DISTINCT EIGENVALUES  
 (I.E.,  $r=n$  AND  $m_1=m_2=\dots=m_n=1$ ) THEN  
 $M_1=M_2=\dots=1$  AND  $A$  IS DIAGONALIZABLE.

TO REMEMBER ALL OF THIS IN A PICTURE, IMAGINE THAT  
 EACH DISTINCT EIGENVALUE  $\lambda_i$  "RESERVES" A PART OF  
 $\mathbb{R}^n$  FOR ITSELF, AND ITS EIGENSPACE  $E_{\lambda_i}$  MUST SIT  
 INSIDE THIS RESERVED SPACE (AND TAKES UP ALL OF IT  
 IF THE GEOMETRIC MULT. OF  $\lambda_i$  MATCHES ITS ALGEBRAIC  
 MULT.). THAT IS,



$\lambda_1, \dots, \lambda_r \in \mathbb{C}$   
 DISTINCT EIGENVALUES.

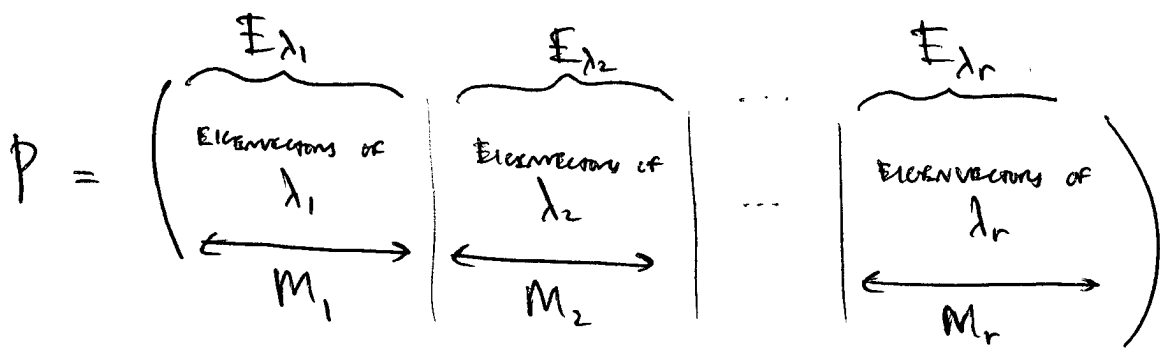
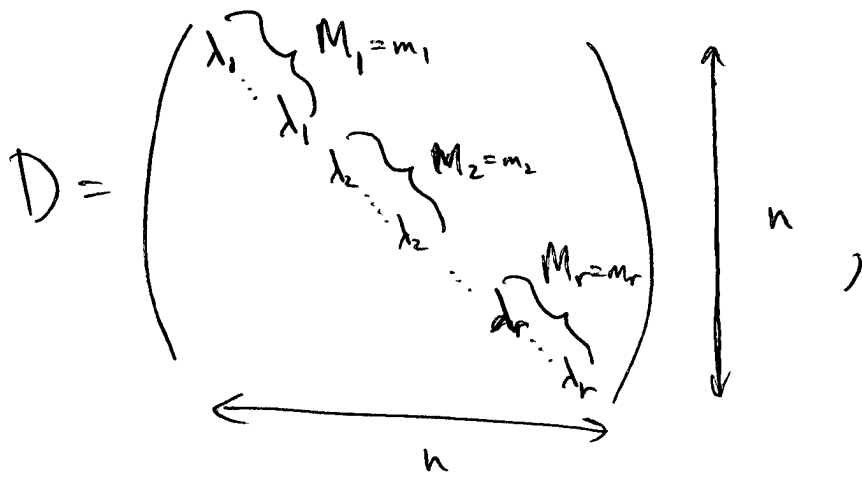
$A$  DIAGONALIZABLE  $\iff M_i = m_i$  FOR ALL  $i$ .

Q: WHAT IF  $M_i < m_i$  FOR SOME  $i$ ?

A:  $A$  IS NOT DIAGONALIZABLE, BUT IS ALMOST  
 DIAGONALIZABLE.

# JORDAN CANONICAL FORM (4.9) :

IF  $A$  IS DIAGONALIZABLE, THEN  $A = PDP^{-1}$ , WHERE



Q: IF  $M_i \neq m_i$  FOR ALL  $i$ , WE ARE "MISSING" EIGENVECTORS.

CAN WE SUBSTITUTE THESE WITH A MORE GENERAL NOTION OF EIGENVECTOR?

A: YES. THIS LEADS TO GENERALIZED EIGENVECTORS (POWER VECTORS).

SUPPOSE EIGENVALUE  $\lambda$  OF  $A$  HAS ALG. MULT.  $m$ , GEOM. MULT.  $M$ .

•  $E_\lambda = \text{Ker}(A - \lambda I)$  HAS BASIS  $\mathcal{B}_\lambda = \{\underline{b}_1, \dots, \underline{b}_M\}$

↑ EIGENSPACE ASSOCIATED TO  $\lambda$  AND DIMENSION  $M \leq m$ .

•  $\tilde{E}_\lambda = \text{Ker}((A - \lambda I)^m)$  HAS BASIS  $\tilde{\mathcal{B}}_\lambda = \{\underline{b}_1, \dots, \underline{b}_M, \underline{\xi}_1, \dots, \underline{\xi}_{m-M}\}$

↑ GENERALIZED EIGENSPACE ASSOCIATED TO  $\lambda$ . AND DIMENSION  $m$ . GENERALIZED EIGENVECTORS.

• NOTE THAT  $E_\lambda \subseteq \tilde{E}_\lambda$  SINCE IF

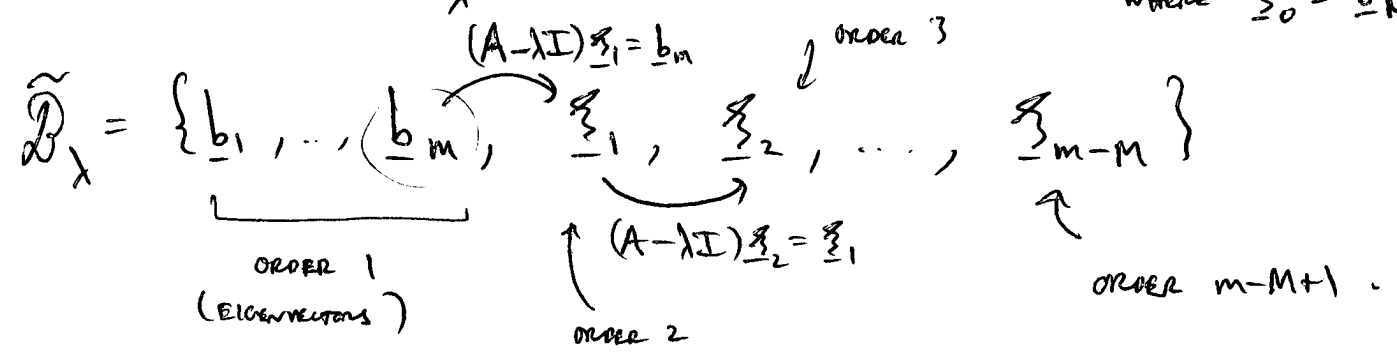
$$(A - \lambda I) \underline{v} = \underline{0} \quad \text{THEN} \quad (A - \lambda I)^m \underline{v} = \underline{0}.$$

• IT CAN BE SHOWN THAT IF  $(A - \lambda I)^p \underline{v} = \underline{0}$  FOR ANY  $p \in \mathbb{N}$ , THEN  $\underline{v} \in \tilde{E}_\lambda$ .

•  $\underline{v}$  IS CALLED A GENERALIZED EIGENVECTOR (POWER VECTOR)

IF  $(A - \lambda I)^p \underline{v} = \underline{0}$  FOR SOME  $p$ . THE MINIMUM VALUE OF  $p$  SUCH THAT THIS IS TRUE IS CALLED THE ORDER OF  $\underline{v}$ . NOTE THAT IF  $\underline{v}$  IS OF ORDER  $p \geq 1$ , THEN  $\underline{w} = (A - \lambda I) \underline{v}$  IS OF ORDER  $p - 1$ .

HOW TO FIND  $\tilde{D}_\lambda$ ? DEFINE  $\underline{x}_i$  BY  $(A - \lambda I) \underline{x}_i = \underline{x}_{i-1}$ ,  $i=1, \dots$  WHERE  $\underline{x}_0 = \underline{b}_m$ .



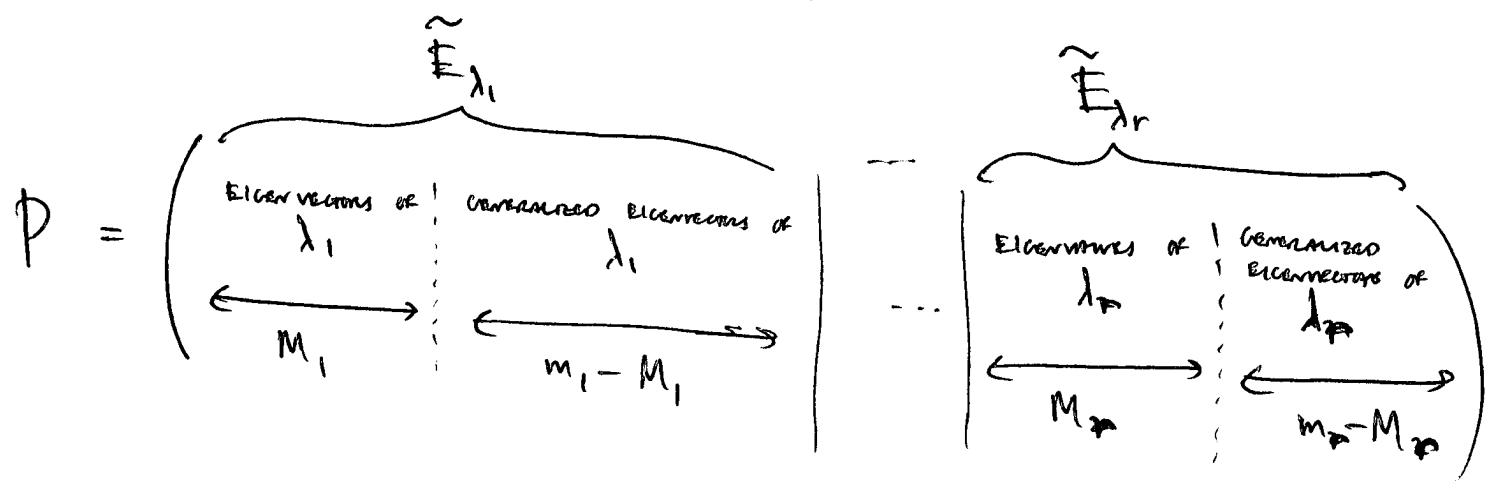
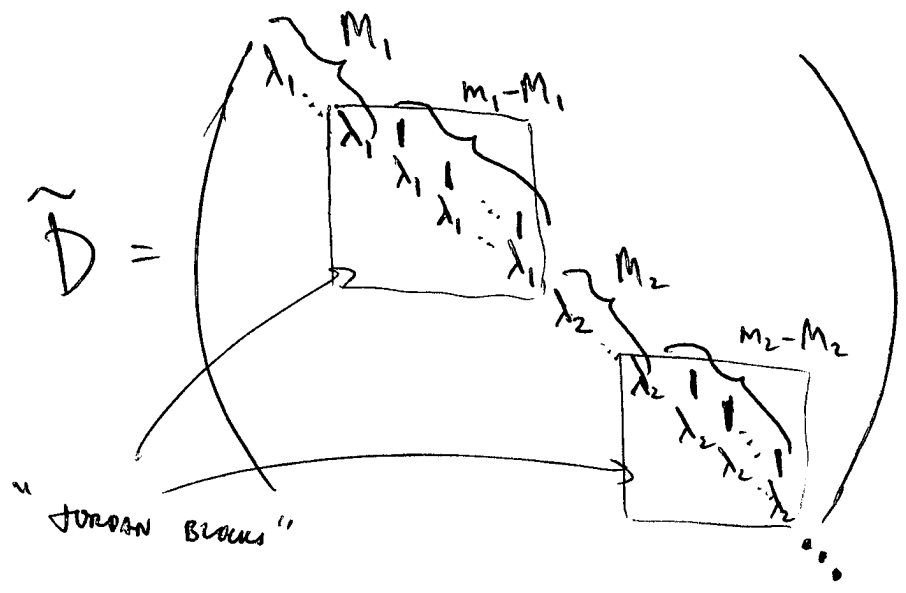
THEN, SINCE  $(A - \lambda I) \underline{x}_i = \underline{x}_{i-1} \Rightarrow A \underline{x}_i = \lambda \underline{x}_i + \underline{x}_{i-1}$ ,

$$[A \underline{b}_i]_{\tilde{D}_\lambda} = \lambda_i \underline{e}_i \quad \text{AND} \quad [A \underline{x}_i]_{\tilde{D}_\lambda} = \lambda \underline{e}_{m+i} + \underline{e}_{m+i-1}.$$

$(i=1, \dots, M)$    $(i=1, \dots, m-M)$

THIS IMPLIES THAT FOR ANY  $A \in M_{n,n}$ ,

$A = P \tilde{D} P^{-1}$  WHERE  $\tilde{D} = [A]_{\tilde{B}}$  TAKES THE FORM



EX:  $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ . (NOTE: WE SAW IN A PREVIOUS VIDEO THAT THIS MATRIX IS NOT DIAGONALIZABLE.)

$P_A(\lambda) = \lambda^2 = 0 \Rightarrow \lambda = 0$ .

$E_0$ :  $A - 0I = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \Rightarrow \underline{\xi} = \xi_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow \{(1,0)^T\}$  BASIS OF  $E_0$ .

i.e.,  $\lambda=0$  HAS  $m=2$ , BUT  $M=1$ .

WHAT TO DO?

LOOK FOR GENERALIZED EIGENVECTORS,

$\mathbb{R}^2$  HAS BASIS  $\tilde{\mathcal{B}}_0 = \{ \underline{b}, \underline{\xi} \}$ , WHERE

$$\underline{b} = (1, 0)^T \in E_0, \text{ AND}$$

$$(A - 0I)\underline{\xi} = \underline{b} \Rightarrow \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \underline{\xi} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\Rightarrow \underline{\xi} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

↑ GENERALIZED EIGENVECTOR OF ORDER 2.

$$\text{SO, } \tilde{D} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad P = \begin{pmatrix} \underline{b} & \underline{\xi} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I.$$

IN RETROSPECT, THIS IS OBVIOUS SINCE  $A$  IS ALREADY IN JORDAN FORM!

EX.  $A = \begin{pmatrix} 3 & 1 & -2 \\ -1 & 0 & 5 \\ -1 & -1 & 4 \end{pmatrix}$

$$\begin{aligned} \Rightarrow P_A(\lambda) &= \det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 1 & -2 \\ -1 & -\lambda & 5 \\ -1 & -1 & 4-\lambda \end{vmatrix} \\ &= (3-\lambda) \begin{vmatrix} -\lambda & 5 \\ -1 & 4-\lambda \end{vmatrix} - (-1) \begin{vmatrix} 1 & -2 \\ -1 & 4-\lambda \end{vmatrix} + (-1) \begin{vmatrix} 1 & -2 \\ -\lambda & 5 \end{vmatrix} \\ &= (3-\lambda) [\lambda^2 - 4\lambda + 5] + (2-\lambda) + (2\lambda - 5) \\ &= (\lambda - 3) [(-\lambda^2 + 4\lambda - 5) + 1] \\ &= -(\lambda - 3)(\lambda - 2)^2 = 0 \Rightarrow \lambda = 3, \lambda = 2. \end{aligned}$$

$$\underline{\underline{E_3}}: A - 3I = \begin{pmatrix} 0 & 1 & -2 \\ -1 & -3 & 5 \\ -1 & -1 & 1 \end{pmatrix} \xrightarrow{\text{ref}} \begin{pmatrix} \boxed{1} & 0 & 1 \\ 0 & \boxed{1} & -2 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow \underline{\underline{x}} = x_3 \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix} \Rightarrow \{(-1, 2, 1)^T\} \text{ BASIS OF } E_3.$$

$$\underline{\underline{E_2}}: A - 2I = \begin{pmatrix} 1 & 1 & -2 \\ -1 & -2 & 5 \\ -1 & -1 & 2 \end{pmatrix} \xrightarrow{\text{ref}} \begin{pmatrix} \boxed{1} & 0 & 1 \\ 0 & \boxed{1} & -3 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow \underline{\underline{x}} = x_3 \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix} \Rightarrow \{(-1, 3, 1)^T\} \text{ BASIS OF } E_2.$$

so,  $\lambda = 3$  HAS  $\begin{cases} \text{ALG. MULT. } 1 \\ \text{GEOM. MULT. } 1 \end{cases}$

$\lambda = 2$  HAS  $\begin{cases} \text{ALG. MULT. } 2 \\ \text{GEOM. MULT. } 1 \end{cases} \Rightarrow A \text{ NOT DIAGONALIZABLE.}$

WHAT IS  $\tilde{E}_2$ ?

$\tilde{E}_2$ : HAS BASIS  $\tilde{\mathcal{B}}_2 = (\underline{b}, \underline{x})$ , where  $\underline{b} = (-1, 3, 1)^T \in E_2$ .

$$(A - 2I)\underline{x} = \underline{b}$$

$$\Rightarrow \left( \begin{array}{ccc|c} 1 & 1 & -2 & -1 \\ -1 & -2 & 5 & 3 \\ -1 & -1 & 2 & 1 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} \boxed{1} & 0 & 1 & 1 \\ 0 & \boxed{1} & -3 & -2 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$\Rightarrow \begin{cases} x_1 = 1 - x_3 \\ x_2 = -2 + 3x_3 \\ x_3 \text{ FREE} \end{cases} \Rightarrow \underline{x} = \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix}$$

LET  $\underline{x}_3 = 0$  (ONLY NEED ONE SOLN.)

$$\Rightarrow \underline{x} = (1, -2, 0)^T. \text{ (GENERALIZED EIGENVECTOR)}$$

Therefore,

$$A = P \tilde{D} P^{-1} \quad \text{with} \quad D = \begin{pmatrix} 3 & & \\ & 2 & \\ & & 1 \\ & & & 2 \end{pmatrix}$$

$$P = \begin{pmatrix} -1 & -1 & 1 \\ 2 & 3 & -2 \\ 1 & 1 & 0 \end{pmatrix}$$