

What's a ^{smooth} surface?

Something that locally looks like \mathbb{R}^2 .

1) Graphs of smooth functions $f: \mathbb{R}^2 \rightarrow \mathbb{R}$.
 $(x, y, f(x, y))$ or $(x, f(x, z), z)$ or
 $(f(y, z), y, z)$.

2) Image of smooth $\sigma: \mathbb{R}^2 \rightarrow \mathbb{R}^3$
with $\text{Rank } D\sigma = 2 \Leftrightarrow \sigma_u \times \sigma_v \neq 0$.

3) Level set of smooth $F: \mathbb{R}^3 \rightarrow \mathbb{R}$.

with $\nabla F \neq 0$ on level set,

(Local)

Equivalence via IFT.

$$\text{Unit normal vector} = \pm \frac{\sigma_u \times \sigma_v}{|\sigma_u \times \sigma_v|}$$

S is orientable if consistent choice.

Level sets are orientable.

(Pick \vec{N} in ∇F direction).

Examples.

Quadratics: level sets of $F(x) = x^T A x + b^T x$.

Shape depends mostly on e-vals of A .

(+,+,+) : ellipsoid (or pt. or \emptyset)

(-, -, -)

(+, +, -) } hyperboloid of 1 or 2 sheets
(-, -, +) } or double cone.

Paraboloids, cylinders, planes, lines, pts, occur when
e-val(s) = 0.

Ruled surfaces \equiv collections of lines.

$$\sigma(u, v) = \vec{\gamma}(u) + v \vec{\delta}(u)$$

$$D\sigma = \begin{pmatrix} \dot{\gamma} + v\dot{\delta} \\ \delta \end{pmatrix}$$

E.g.

$$z = xy$$

$$\gamma(u) = (u, 0, 0)$$

$$\delta(u) = (0, 1, u)$$

$$\sigma(u, v) = (u, v, uv)$$

$$x^2 + y^2 - z^2 = 1$$

$$\gamma(u) = (\cos u, \sinh(u), 0)$$

$$\delta(u) = (-\sinh u, \cos(u), \pm 1)$$

Generalized cylinder ($\delta = \text{const}$)

"

cone

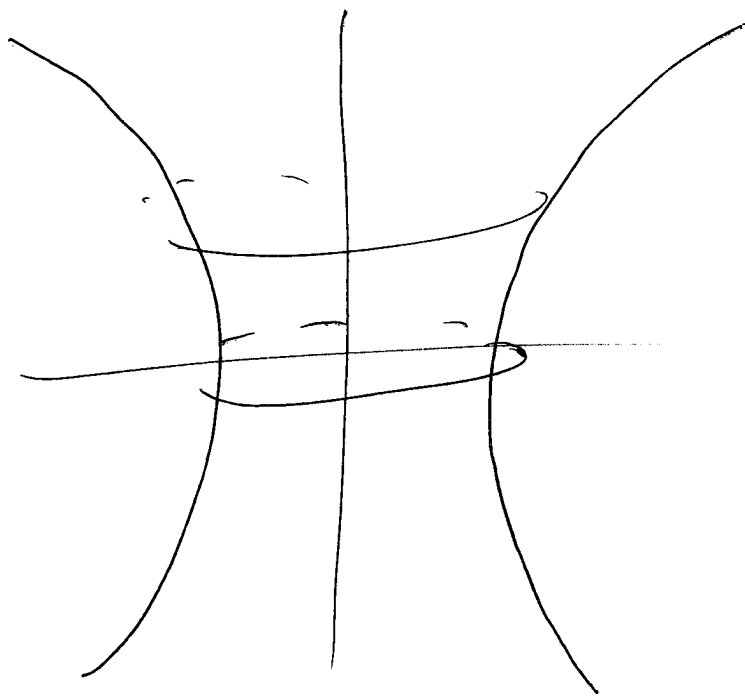
($\delta = \gamma$)

Surfaces of revolution

$$\gamma(u) = (f(u), 0, g(u))$$

$$\sigma(u, v) = (f(u) \cos v, f(u) \sin v, g(u))$$

Ex: $f(u) = \cosh u, \quad g(u) = \sinh u$

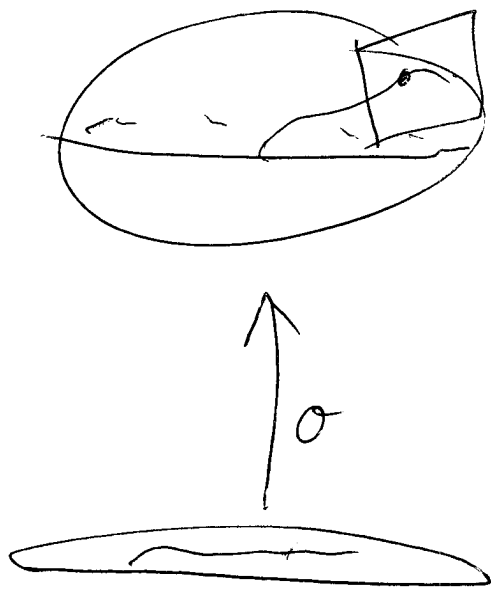


hyperboloid of
1 sheet.

Compact surfaces

Classification: $S = S^2, T^2,$ or ~~S^2~~
 g -holed torus.

All are orientable.



$$T_p S = \{ \text{all possible velocities through } p \}$$

$$= \text{Span} \{ \sigma_u, \sigma_v \} \subset \mathbb{R}^3$$

First Fundamental Form (FFF) is inner product restricted to $T_p S$.

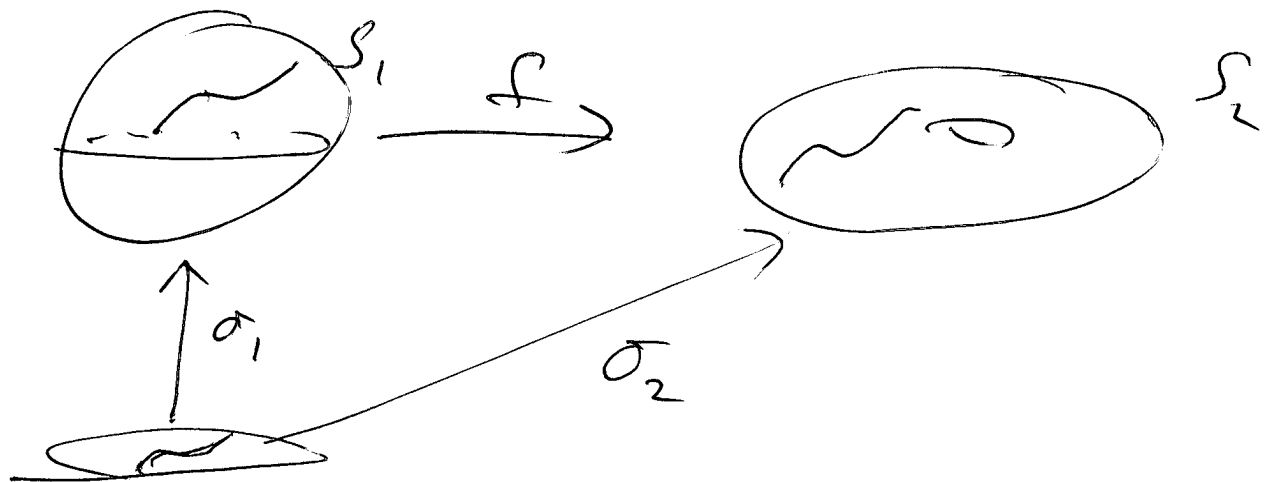
Work in σ_u, σ_v basis,

$$\begin{pmatrix} E & F \\ F & G \end{pmatrix} = \begin{pmatrix} \sigma_u \cdot \sigma_u & \sigma_u \cdot \sigma_v \\ \sigma_v \cdot \sigma_u & \sigma_v \cdot \sigma_v \end{pmatrix}$$

$$ds^2 = E (du)^2 + 2F du dv + G (dv)^2$$

$$\text{Length} = \int \sqrt{E(\dot{u})^2 + 2F\dot{u}\dot{v} + G(\dot{v})^2} dt$$

Isometries preserve FFI.



Thm f is a ^{local} isometry if, for any chart σ_1 , $\begin{pmatrix} E_2 & F_2 \\ F_2 & G_2 \end{pmatrix} = \begin{pmatrix} E_1 & F_1 \\ F_1 & G_1 \end{pmatrix}$, where

$$\sigma_2 = f \circ \sigma_1$$

Sphere: ~~$\sigma(u, v) =$~~

$$\sigma(\theta, \phi) = (\cos\theta \cos\phi, \cos\theta \sin\phi, \sin\theta)$$

$$ds^2 = (d\theta)^2 + \cos^2\theta (d\phi)^2$$

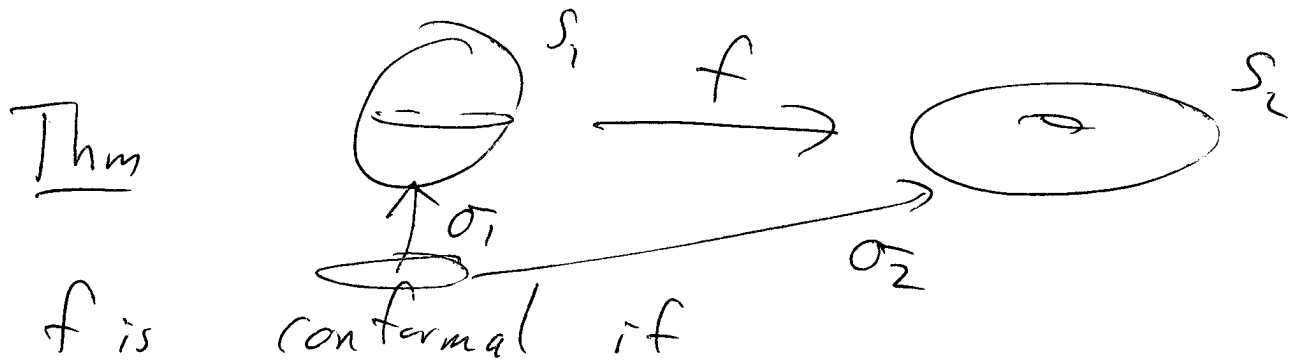
$$FFF = \begin{pmatrix} 1 & 0 \\ 0 & \cos^2\theta \end{pmatrix}$$

Stereographic coordinates

$$\sigma(u, v) = \left(\frac{2u}{u^2+v^2+1}, \frac{2v}{u^2+v^2+1}, \frac{u^2+v^2-1}{u^2+v^2+1} \right)$$

$$ds^2 = (du^2 + dv^2) \cdot \frac{4}{(u^2+v^2+1)^2}$$

Conformal maps preserve angle.



$$\begin{pmatrix} E_2 & F_2 \\ F_2 & G_2 \end{pmatrix} = h(u,v) \begin{pmatrix} E_1 & F_1 \\ F_1 & G_1 \end{pmatrix}$$

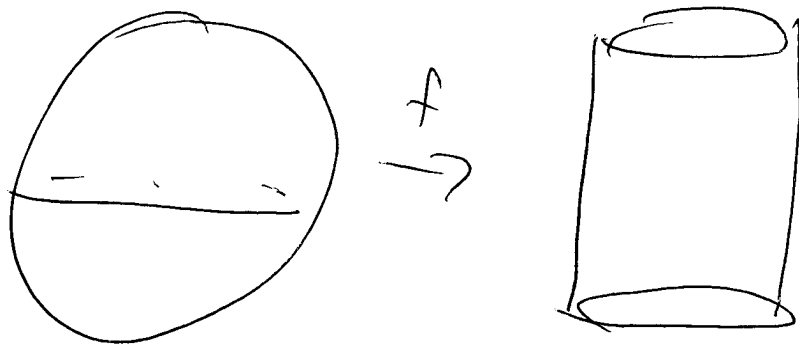
Deep fact All surfaces have (locally)
conformal coordinates.

When does a map preserve area?

Ans: When $E_2 G_2 - F_2^2 = E_1 G_1 - F_1^2$.

$$\text{Area} = \iint \sqrt{EG - F^2} \, du \, dv$$

Application



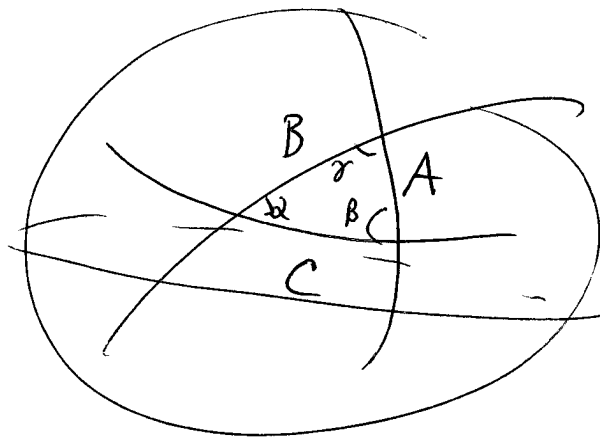
$$(x, y, z) \rightarrow \left(\frac{x}{\sqrt{x^2 + y^2}}, \frac{y}{\sqrt{x^2 + y^2}}, z \right)$$

$$ds_1^2 = \sin^2 \theta d\phi^2 + d\theta^2$$

$$\begin{aligned} ds_2^2 &= \cos^2 \theta d\theta^2 + d\phi^2 \\ &= (dz)^2 + (d\phi)^2 \end{aligned}$$

$$\begin{aligned} z &= \sin \theta \\ dz &= \cos \theta d\theta \end{aligned}$$

Spherical geometry:

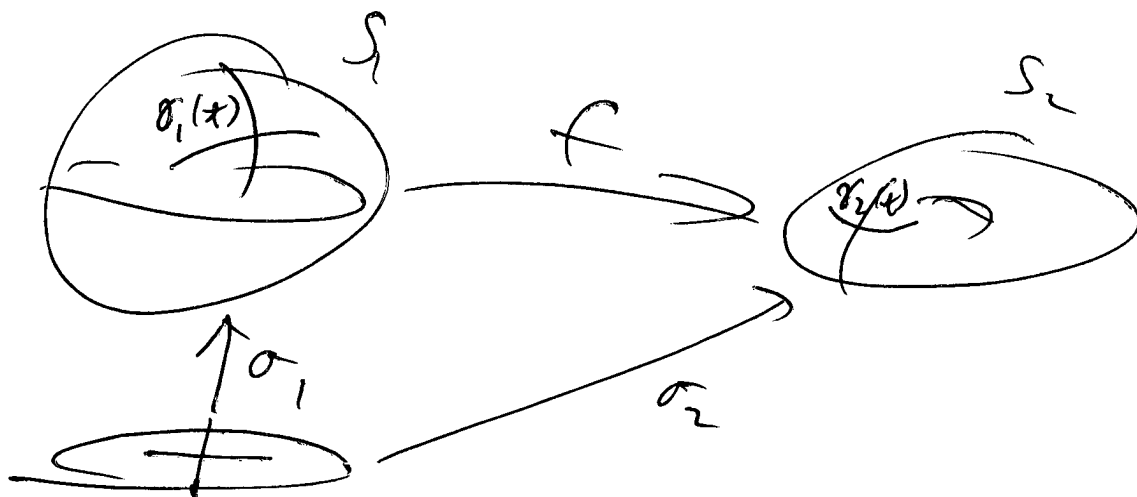


$$\alpha + \beta + \gamma = \pi + \text{Area } \Delta$$

$$\cos C = \cos A \cos B + \sin A \sin B \cos \gamma$$

$$\frac{\sin \alpha}{\sin A} = \frac{\sin \beta}{\sin B} = \frac{\sin \gamma}{\sin C}$$

Suppose ϕ is local isometry.



Consider path $(u, v) = (t, 0)$

Speed of γ_1 at $t=0$ is $|\sigma_{1,u}| = \sqrt{E_1}$.

Speed of γ_2 is $\sqrt{E_2}$. So $\sqrt{E_1} = \sqrt{E_2}$, so

$$E_1 = E_2.$$

Now consider path $(u, v) = (0, t)$

Now consider $(u, v) = (t, t)$

$$G_1 = G_2$$

$$\sqrt{E_1 + G_1 + 2F_1} = \sqrt{E_2 + G_2 + 2F_2}$$

$$\begin{pmatrix} u & v \end{pmatrix} \begin{pmatrix} E & F \\ F & G \end{pmatrix} \begin{pmatrix} \dot{u} \\ \dot{v} \end{pmatrix}$$

$$\int \sqrt{E_1 \dot{u}^2 + G_1 \dot{v}^2 + 2F_1 \dot{u} \dot{v}} dt$$

vs . . .