

**LECTURE 13**  
**MATH 242**

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1.  $J$ -HOLOMORPHIC CURVES

1.1. **Definitions.** Recall we were considering a symplectic manifold with an  $\omega$ -compatible acs  $(M^{2n}, \omega, J)$ . Then a  $J$ -holomorphic map is  $u : (\Sigma, j) \rightarrow (M, \omega, J)$  such that

$$J \circ du = du \circ j .$$

Then we saw that if  $\Sigma$  is compact, then

- (1)  $\text{area}(u) = \langle u_*[\Sigma], [\omega] \rangle$
- (2)  $u$  minimizes area among smooth maps  $u' : \Sigma' \rightarrow M$  in the same homology class.

**Definition 1.** A  $J$ -holomorphic curve is a  $J$ -holomorphic map  $u : (\Sigma, j) \rightarrow (M, \omega, J)$  modulo the equivalence relation that  $u$  is equivalent to  $u' : (\Sigma', j') \rightarrow (M, \omega, J)$  if there exists a biholomorphic map

$$\varphi : (\Sigma, j) \xrightarrow{\cong} (\Sigma', j')$$

such that  $u = u' \circ \varphi$ .

*Remark 1.* An embedded  $J$ -holomorphic curve is determined by its image in  $M$ , and an embedded surface  $\Sigma$  in  $M$  is (the image of) an embedded  $J$ -holomorphic curve iff  $J : T\Sigma \circlearrowright$ .

**Definition 2.** A  $J$ -holomorphic curve  $u$  is *multiply covered* if there exists

$$\begin{array}{ccc} (\Sigma, j) & \xrightarrow{u} & (M, \omega, J) \\ \downarrow p & \nearrow u' & \\ (\Sigma', j') & & \end{array}$$

where the map  $p$  is a branched cover of degree  $> 1$ .

Recall a branched cover is locally modelled on  $\mathbb{C} \rightarrow \mathbb{C}$  where  $z \mapsto z^m$ .

**Definition 3.**  $u$  is simple if it is not a multiple cover.

Note simple does not imply embedded, i.e. there can be singularities.

**Definition 4.** A  $J$ -holomorphic curve with  $k$  marked points consists of a holomorphic map

$$u : (\Sigma, j) \rightarrow (M, \omega, J)$$

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together with  $z_1, \dots, z_k \in \Sigma$  distinct modulo

$$\begin{array}{ccc} (\Sigma, j, z_1, \dots, z_k) & \xrightarrow{u} & (M, \omega, j) \\ \downarrow & \nearrow^{u'} & \\ (\Sigma', j', z'_1, \dots, z'_k) & & \end{array}$$

where the unlabelled map (which brings  $z_i \mapsto z'_i$ ) is biholomorphic.

1.2. **Examples.**

**Example 1.** Algebraic curves in  $\mathbb{C}\mathbb{P}^2$  equipped with  $J_{\text{std}}$  are images of holomorphic maps.

**Lemma 1.** *If  $u : (\Sigma, j) \rightarrow (M, \omega, J)$ ,  $\Sigma$  is connected, compact, and  $u_*[\Sigma] = 0 \in H_2(M; \mathbb{R})$  then  $u$  is constant.*

*Proof.* By the lemma from last lecture,  $\text{area}(u) = 0$ . Choose local coordinate  $z = s + it$  on  $\Sigma$ . This means

$$j \frac{\partial}{\partial s} = \frac{\partial}{\partial t}.$$

Locally the condition of being a holomorphic curve then means that

$$\frac{\partial u}{\partial t} = J \frac{\partial u}{\partial s}$$

and the area integrand can be written:

$$\begin{aligned} \text{integrand} &= \sqrt{g \left( \frac{\partial u}{\partial s}, \frac{\partial u}{\partial s} \right) g \left( \frac{\partial u}{\partial t}, \frac{\partial u}{\partial t} \right) - g \left( \frac{\partial u}{\partial s}, \frac{\partial u}{\partial t} \right)^2} |ds dt| \\ &= \sqrt{\omega \left( \frac{\partial u}{\partial s}, J \frac{\partial u}{\partial s} \right) \omega \left( \frac{\partial u}{\partial t}, J \frac{\partial u}{\partial t} \right) - \omega \left( \frac{\partial u}{\partial s}, J \frac{\partial u}{\partial t} \right)^2} |ds dt| \\ &= \sqrt{\omega \left( \frac{\partial u}{\partial s}, \frac{\partial u}{\partial t} \right)^2} |ds dt| \\ &= \left| \frac{\partial u}{\partial s} \right|^2 |ds dt| = \left| \frac{\partial u}{\partial t} \right|^2 |ds dt| \end{aligned}$$

but these are non-negative everywhere, so since the area is 0 we have

$$\frac{\partial u}{\partial s} \equiv \frac{\partial u}{\partial t} \equiv 0$$

which implies  $u$  is constant. □

**Example 2.** Fix a compact surface  $(\Sigma, j)$  and fix  $(M, \omega_M, J_M)$ . Consider the product

$$X = \left( \Sigma \times M, \underbrace{\omega_\Sigma \oplus \omega_M}_\omega, \underbrace{j \oplus J_M}_J \right).$$

If  $p \in M$  then we can look at maps

$$u_p : \Sigma \rightarrow X$$

which send  $z \mapsto (z, p)$ . This map is  $J$ -holomorphic.

**Claim 1.** Every  $J$ -holomorphic curve in  $X$  in the homology class  $[\Sigma] \times [\{\text{pt}\}]$  is of the form  $u_p$ .

*Proof.* Let  $u' : (\Sigma', j') \rightarrow X$  be a  $J$ -holomorphic curve. Suppose  $u'_*[\Sigma'] = [\Sigma] \times [\text{pt}]$ . Then we want to show that  $u'$  is equivalent to some  $u_p$ .

Let  $\pi : X \rightarrow M$  denote the projection. Then  $\pi \circ u' : \Sigma' \rightarrow M$  is  $J_M$ -holomorphic and

$$(\pi \circ u')_*[\Sigma'] = 0 .$$

By the previous lemma,  $\pi \circ u'$  is constant. Denote its image by  $\{p\}$ . Then

$$\text{im}(u') \subseteq \Sigma \times \{p\} .$$

Let  $\rho : X \rightarrow \Sigma$  denote the other projection. Then  $\rho \circ u' : \Sigma' \rightarrow \Sigma$  is  $j$ -holomorphic. We have

$$(\rho \circ u')_*[\Sigma'] = [\Sigma] .$$

Then  $\rho \circ u'$  is a degree 1 branch cover, and hence a diffeomorphism. So  $\rho \circ u'$  is a biholomorphic map showing  $u' \sim u_p$ . So the diagram is

$$\begin{array}{ccc} \Sigma' & \xrightarrow{u'} & X \\ \rho \circ u' \downarrow & \nearrow u_p & \\ \Sigma & & \end{array} .$$

□

## 2. GROMOV NON-SQUEEZING

2.1. **Strategy.** Start with a symplectic embedding  $\varphi : B(r) \hookrightarrow Z(r)$  where

$$\begin{aligned} B(r) &= \{z \in \mathbb{C}^n \mid \pi |z|^2 \leq r\} \\ Z(r) &= \{z \in \mathbb{C}^n \mid \pi |z_1|^2 \leq R\} . \end{aligned}$$

Now we go on a search for a holomorphic curve.

First we fix some notation. For  $A \in H_2(X)$ , we write

$$m_{g,k}^J(X, \omega, A)$$

for the collection of  $J$ -holomorphic curves  $u$  which have  $k$  marked points, are in the homology class  $A$ , and with domain a genus  $g$  compact Riemann surface. For  $i = 1, \dots, k$  we write  $\text{ev}_i$  for the evaluation map:

$$m_{g,k}^J \xrightarrow{\text{ev}_i} X$$

$$(u, \Sigma, z_1, \dots, z_k) \longmapsto u(z_i) .$$

We can write  $Z(R)$  as the product of the disk of area  $R$  with  $\mathbb{C}^{n-1}$ , and then we have a symplectic inclusion

$$Z(R) \hookrightarrow S^2(R + \epsilon) \times \mathbb{C}^{n-1}$$

where  $S^2(R + \epsilon)$  is a 2-sphere with a symplectic form of area  $R + \epsilon$ . Let  $\hat{\varphi} : B(r) \hookrightarrow S^2(R + \epsilon) \times \mathbb{C}^{n-1}$  be the composition. Since  $B(r)$  is compact, its image is bounded. Let  $T = \mathbb{C}^{n-1}/c\mathbb{Z}^{2n-2}$  where  $c \gg 0$ . Then the composition

$$\tilde{\varphi} : B(r) \hookrightarrow S^2(R + \epsilon) \times \mathbb{C}^{n-1} \rightarrow S^2 \times T$$

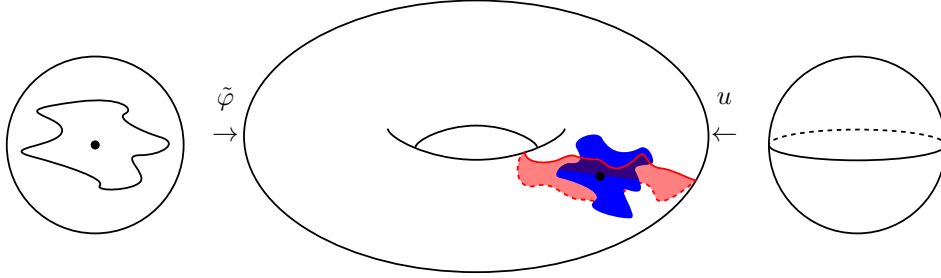


FIGURE 1. On the left we have  $\tilde{\varphi} : B(r) \rightarrow S^2 \times T$  with blue image. Then we have a map from  $u : S^2 \rightarrow S^2 \times T$ . The image of this map (in red) contains the center of the image of the ball. Then the inverse image under  $u$  of the image of  $\tilde{\varphi}$ ,  $\Sigma$ , is the domain of the map  $\psi := \tilde{\varphi}^{-1} \circ u$ . The region outlined inside of  $B(r)$  is  $(\tilde{\varphi}^{-1} \circ u)(\Sigma)$ .

is still a symplectic embedding.

Let  $J$  be a compatible acs on  $S^2(R + \epsilon) \times T$  such that on  $\tilde{\varphi}(B(r))$  it agrees with  $\tilde{\varphi}_*(J_0)$  where  $J_0$  is the standard acs on  $\mathbb{C}^n$ . We can do this because the space of compatible acs is contractible.

Consider  $m_{0,1}^J(S^2(R + \epsilon) \times T, \omega, [S^2] \times [\text{pt}])$ . So these are holomorphic spheres in this manifold with one marked point. Then the evaluation map  $\text{ev}_1$  maps

$$\text{ev}_1 : m_{0,1}^J(S^2(R + \epsilon) \times T, \omega, [S^2] \times [\text{pt}]) \rightarrow S^2(R + \epsilon) \times T .$$

The key point which we will prove next time is:

**this map is surjective!**

That is, for every  $p \in S^2 \times T$ , there is a  $J$ -holomorphic sphere in the class  $[S^2] \times [\text{pt}]$  “going through”  $p$ .

Gromov nonsqueezing follows (almost) immediately from this. We can deduce nonsqueezing as follows. Let  $u : S^2 \rightarrow S^2 \times T$  be a curve given by the key fact with  $\text{im}(u) \ni \tilde{\varphi}(0)$ , i.e. a curve containing the center of the ball. Let

$$\Sigma = u^{-1}(\tilde{\varphi}(B(r))) \subset S^2 .$$

Consider the map

$$\tilde{\varphi}^{-1} \circ u : \Sigma \rightarrow B(r) ,$$

which is actually  $J_0$ -holomorphic. The picture is as in fig. 1.

Now let’s see what we ended up with.<sup>1</sup> The upshot is that, after some tweaking to get boundary transversality, we have  $(\Sigma, j)$  a compact Riemann surface with boundary, and a  $J_0$ -holomorphic map  $\psi = \tilde{\varphi}^{-1} \circ u$  which maps

$$\Sigma \rightarrow B(r) \qquad \partial\Sigma \rightarrow \partial B(r) .$$

And in particular,

$$\text{area}(\psi) < R + \epsilon .$$

Now we have the following lemma:

<sup>1</sup>Professor Hutchings says that at this point we should thank  $J$ -holomorphic curves and put some money in the tip jar.

**Lemma 2** (Monotonicity lemma for minimal surfaces). *Let  $\Sigma$  be a compact Riemann surface with boundary. If  $\psi : \Sigma \rightarrow B(r)$ ,  $0 \in \text{im}(\psi)$ , and  $\psi$  minimizes area relative to its boundary, then  $\text{area}(\psi) \leq r$ .*

Such inequalities are sometimes called reverse isoperimetric inequalities.

Now by lemma 2, we have  $\text{area}(\psi) \leq r$ , which implies  $r < R + \epsilon$ . But since  $\epsilon$  is arbitrary we have  $r \leq R$  so we are done.

So next time we will prove lemma 2, and then we have to think about why such a holomorphic curve exists, i.e. we will prove that this evaluation map is surjective.