

LECTURE 22
MATH 242

LECTURE: PROFESSOR MICHAEL HUTCHINGS
NOTES: JACKSON VAN DYKE

1. FLOER HOMOLOGY OF HAMILTONIAN SYMPLECTOMORPHISMS

1.1. **Morse homology.** Recall what we discussed last week. Let X be a finite dimensional smooth manifold. Then we have a Morse function $f : X \rightarrow \mathbb{R}$, the critical points of this function, the Hessian, and gradient flow lines. Then all of this data gave us Morse homology which is an invariant of X . Now we will do some sort of infinite version of this to get symplectic invariants.

1.2. **Hamiltonian Floer homology.** Let (M, ω) be a closed symplectic manifold. Consider a one-parameter family of Hamiltonians $\{H_t\}_{t \in [0,1]}$ i.e. $H_t : M \rightarrow \mathbb{R}$. WLOG let $H_1 = H_0$ and $\{H_t\}_{t \in [0,1]}$ is the restriction of a family $\{H_t\}_{t \in \mathbb{R}}$ with $H_{t+1} = H_t$.

Let $\varphi_t : M \rightarrow M$ be the time t flow. I.e. $\varphi_0 = \text{id}_M$ and

$$\frac{\partial}{\partial t} \varphi_t(x) = X_{H_t}(\varphi_t(x)) .$$

Then we are interested in fixed points of φ_1 . A useful way to think of this is that we have a natural bijection:

$$\text{Fix}(\varphi_1) \longleftrightarrow \{\gamma : \mathbb{R}/\mathbb{Z} \rightarrow M \mid \gamma'(t) = X_{H_t}(\gamma(t))\}$$

$$\gamma(0) \longleftarrow \gamma$$

From this point of view we are just doing Morse theory on the free loop space of M .

Defining Hamiltonian Floer homology in full generality is very complicated, so to simplify things we will make some assumptions. We will talk later about how to remove them. Assume M is *symplectically aspherical*. This means that

$$\langle c_1(TM), A \rangle = \langle [\omega], A \rangle = 0$$

for all $A \in \pi_2(M)$. E.g. $\pi_2(M) = 0$ would do the trick. Let \mathcal{L} be the space of contractible smooth loops $\gamma : \mathbb{R}/\mathbb{Z} \rightarrow M$. We will be doing Morse homology on \mathcal{L} .

Date: April 16, 2019.

1.3. Symplectic action functional. Define the *symplectic action functional* $\mathcal{A} : \mathcal{L} \rightarrow \mathbb{R}$ by

$$\mathcal{A}(\gamma) = \int_0^1 H_t(\gamma(t)) dt + \int_{D^2} u^* \omega$$

where $u : D^2 \rightarrow M$ is a map with

$$u(e^{2\pi it}) = \gamma(t) .$$

This disk exists because we assumed γ is contractible. This integral doesn't depend on the choice of disk because of the symplectically aspherical assumption. If we replace it with some other $u' : D^2 \rightarrow M$ then

$$\int_{D^2} u^* \omega - \int_{D^2} u'^* \omega = \int_{S^2} (u \# u')^* \omega = 0$$

by the assumption.

Lemma 1. γ is a critical point of \mathcal{A} iff $\gamma'(t) = X_{H_t}(\gamma(t))$ for all t .

In particular the critical points are the same as the fixed points of φ_1 which come from contractible loops.

Proof. First notice that

$$T\gamma\mathcal{L} = \Gamma(\gamma^*TM) .$$

So let $\eta \in \Gamma(\gamma^*TM)$. So we have to calculate

$$\begin{aligned} d\mathcal{A}_\gamma(\eta) &= \int_0^1 (dH_t)_{\gamma(t)}(\eta(t)) dt + \int_{S^1} \omega(\eta(t), \gamma'(t)) dt \\ &= \int_0^1 \left(\underbrace{(dH_t)_{\gamma(t)}(\eta(t))}_{\omega(X_{H_t}, \eta(t))} + \omega(\eta(t), \gamma'(t)) \right) dt \\ &= \int_0^1 \omega(X_{H_t} - \gamma'(t), \eta(t)) dt \end{aligned}$$

and $\gamma \in \text{crit}(\mathcal{A})$ iff this integral vanishes for all η iff $X_{H_t} - \gamma'(t) = 0$ for all t . \square

Now we consider the gradient flow lines of \mathcal{A} . To find these we need a metric on \mathcal{L} . Choose an ω -compatible almost complex structure J . Then $\omega(\cdot, J\cdot)$ is a Riemannian metric on M . Now define a metric g on \mathcal{L} as follows. Let $\gamma \in \mathcal{L}$ and $\eta_1, \eta_2 \in \Gamma(\gamma^*TM)$. Then we define the inner product of these to be

$$g(\eta_1, \eta_2) = \int_0^1 \omega(\eta_1(t), J\eta_2(t)) dt .$$

Then the gradient flow equation is as follows. First we calculate $\nabla\mathcal{A}$. The defining property is that

$$d\mathcal{A}(\eta) = g(\nabla\mathcal{A}, \eta) .$$

We calculated that

$$\begin{aligned} d\mathcal{A}(\eta) &= \int_0^1 \omega(X_{H_t} - \gamma'(t), \eta(t)) dt \\ &= \int_0^1 \omega(J(X_{H_t} - \gamma'(t)), J\eta(t)) dt \\ &= g(J(X_{H_t} - \gamma'(t)), \eta) . \end{aligned}$$

Therefore

$$(\nabla\mathcal{A})_\gamma = (t \mapsto J(X_{H_t} - \gamma'(t))) .$$

A path in \mathcal{L} is a map $u : \mathbb{R}_s \times S_t^1 \rightarrow M$ where $u(s, \cdot) \in \mathcal{L}$. Then a gradient flow line of \mathcal{A} is a map

$$u : \mathbb{R} \times S^1 \rightarrow M$$

such that

$$\partial_s u = (\nabla\mathcal{A})(u(s, \cdot)) = J(X_{H_t} - \partial_t u)$$

so the conclusion is that

$$\boxed{\partial_s u + J\partial_t u - X_{H_t} = 0}$$

which is sometimes called “Floer’s equation”.

Remark 1. Note this looks quite a bit like the holomorphic curve equation, i.e. without this Hamiltonian perturbation it is a holomorphic curve.

We could also take J to depend on $t \in S^1$ and then Floer’s equation is

$$\partial_s u + J_t(\partial_t u - X_{H_t}) = 0 .$$

This is often done.

We call solutions “holomorphic cylinders with time-dependent J and Hamiltonian perturbation”.

Bad news: The gradient flow is not defined. Given a smooth loop γ , we generally cannot solve for $u : (-\epsilon, \epsilon) \times S^1 \rightarrow M$ satisfying Floer’s equation with $u(0, \cdot) = \gamma$.

Before Floer, people didn’t think it was possible to do Morse theory on this function for this (and other) reason.¹

Good news: It still makes sense to consider moduli spaces of flow-lines between critical points.

1.4. Moduli spaces of flow-lines. Given $\gamma_+, \gamma_- \in \text{crit}(\mathcal{A})$ define

$$\tilde{m} = \left\{ u : \mathbb{R} \times S^1 \rightarrow M \mid \partial_s u + J_t(\partial_t u - X_{H_t}) = 0, \lim_{s \rightarrow \pm\infty} u(s, t) = \gamma_\pm(t) \right\} .$$

Now \mathbb{R} acts on this set by translating the s coordinate, i.e.

$$(r \cdot u)(s, t) = u(s, t) .$$

Then define

$$m(\gamma_+, \gamma_-) = \tilde{m}(\gamma_+, \gamma_-) / \mathbb{R} .$$

¹But then Floer said “hold my beer” and did it.

1.5. **Autonomous case.** The basic example is what is called the “autonomous case”. This is where

- H_t does not depend on t and is a Morse function $H : M \rightarrow \mathbb{R}$
- J_t does not depend on t and so it defines a metric g on M .

So we have a map

$$\text{crit}(H) \rightarrow \text{crit}(\mathcal{L})$$

which sends p to the constant loop $\gamma(t) = p$. This is surjective possibly after multiplying H by some ϵ sufficiently small.

Let $\eta : \mathbb{R} \rightarrow M$ be a flow line of H , i.e. $\eta'(s) = \nabla H(\eta(s))$. We can calculate

$$\langle \nabla H, V \rangle = dH(V) = \omega(X_H, V) = \omega(\nabla H, Jv) = \omega(-J\nabla H, V)$$

to tell us that

$$\nabla H = JX_H$$

so

$$\eta'(s) = \nabla H(\eta(s)) = JX_H(\eta(s)) .$$

This means that $u(s, t) = \eta(s)$ solves Floer’s equation since

$$\partial_s u + J(\partial_t u - X_{H_t}) = 0 .$$

Assume that all fixed points of φ are nondegenerate. In general we define the Floer chain complex $CF_*(H, J)$ as follows. It is generated over $\mathbb{Z}/2\mathbb{Z}$ (or \mathbb{Z}) by critical points of \mathcal{A} . This is graded by the Conley-Zehnder² index which we will discuss later. In the autonomous case

$$cz(\gamma \equiv p) = \text{ind}(p) - n$$

where $\dim(M) = 2n$.

The differential

$$\partial : CF_*(H, J) \rightarrow CF_{*-1}(H, J) .$$

is defined to be:

$$\partial \gamma_+ = \sum_{cz(\gamma_-) = cz(\gamma_+) - 1} \#m(\gamma_+, \gamma_-) \cdot \gamma_- .$$

Now we have to prove the following facts:

- If J is generic and $\gamma_+ \neq \gamma_-$ then $m(\gamma_+, \gamma_-)$ is a smooth manifold of dimension $cz(\gamma_+) - cz(\gamma_-) - 1$.
- If $cz(\gamma_+) - cz(\gamma_-) = 1$ then $m(\gamma_+, \gamma_-)$ is compact, and hence finite.
- $\partial^2 = 0$

Then we define the Floer homology to be

$$HF_*(H, J) = H_*(CF_*(H, J), \partial) .$$

Then the main theorem to prove is:

Theorem 1. $HF_*(H, J) \simeq H_{*+n}(M; \mathbb{Z}/2\mathbb{Z})$.

Now we know that the chain complex has enough generators to produce this homology, which shows the Arnold conjecture. We actually get a slightly stronger statement. In fact the number of fixed points for which the corresponding loop is contractible is at least the sum of the Betti numbers. So there’s a lot of hard work to be done on this next time.

²This is pronounced like the German ‘z’ which is like an english ‘ts’.

2. FUN DIGRESSION

Let's go back to the finite dimensional case. Suppose we have $f : X \rightarrow \mathbb{R}$ a Morse function with g a metric on X . Suppose we now the pair (f, g) is Morse-Smale. Then $-f : X \rightarrow \mathbb{R}$ is also a Morse function. In fact we have

$$m^f(p_+, p_-) = m^{-f}(p_-, p_+)$$

and the pair $(-f, g)$ is also Morse-Smale. In particular we have an isomorphism of chain complexes³

$$C_*(-f, g) = C^{n-*}(f, g)$$

where $n = \dim X$. This tells us that

$$H_*(-f, g) = H^{n-*}(f, g) ,$$

however we know by continuation maps that in fact we have:

$$H_*(-f, g) \simeq H^{n-*}(f, g) \quad H_*(f, g)$$

continuation

and this is Poincaré duality.

³At least over $\mathbb{Z}/2\mathbb{Z}$. Working over \mathbb{Z} we would have to worry a bit about orientations.