## GEOMETRIC QUANTIZATION

#### LECTURE BY ALI SHEHPER

#### 1. Classical physics

Let Q be our configuration manifold. Write  $M = T^*Q$ . This is our phase space. We will write  $(q, p) \in T^*Q$  for  $q \in Q$  and p in the fiber. This has canonical symplectic form locally given by  $\omega = \sum dp_i \wedge dq_i$ .

The space of classical observables is

(1) 
$$\mathcal{A}_{\rm cl} = \{f: T^*Q \to \mathbb{R}\}$$

Note that there exists  $H \in \mathcal{A}$  such that  $H: T^*Q \to \mathbb{R}_{>0}$ , and for  $f \in \mathcal{A}$ ,

$$\frac{df}{dt} = \{f, H\} = \omega \left( X_f, X_H \right)$$

where  $X_f$  is a vector field defined as

$$\omega\left(X_f,-\right) = df\left(-\right) \;.$$

The canonical transformation (or symplectomorphism) is generated by  $\xi$ :

$$\mathcal{L}_{\xi}\omega = 0 = \underbrace{\iota_{\xi}(d\omega)}_{\xi} + d(\iota_{\xi}\omega) \qquad \qquad \rightsquigarrow \qquad \qquad d(\iota_{\xi}\omega) = 0.$$

(Note  $\mathcal{L}$  denotes the Lie derivative.) Locally  $\omega = dA$ , and  $\iota_{\xi}\omega = df$  for some  $f \in \mathcal{A}$ . Conversely, for any f, define  $\xi$  such that  $\iota_{\xi}\omega = df$ , so each  $f \in \mathcal{A}$  generates a symplectomorphism. We call A the symplectic potential. Note that  $\mathcal{L}_{\xi}A = d\Lambda$ , where  $\Lambda = \iota_{\xi}A - f$ .

# 2. QUANTIZATION

The idea is to take the data  $((M, \omega), \mathcal{A}_{cl})$  and get an irreducible representation  $\mathcal{H} : \mathcal{A}_q \bigcirc$  such that

(2) 
$$\left[\hat{f},\hat{g}\right] = i\hat{\mathcal{O}}$$

for  $\mathcal{O} = \{fg\}$ . This might be too strict for everything in  $\mathcal{A}_q$ , but you at least want it for some. This relation comes from the uncertainty principle.

**Example 1.** If  $M = T^*Q$ ,  $\mathcal{H} = L^2(Q)$ , then  $\hat{q}_i$  acts by multiplication, and  $\hat{p}_i$  by  $-i\nabla_{q_i}$ . For example, f = qp goes to

$$\hat{f} = \frac{\hat{q}\hat{p} + \hat{p}\hat{q}}{2} \ .$$

Notes by: Jackson Van Dyke; all errors introduced are my own.

But what if  $M \neq T^*Q$ ? Geometric quantization will give us

$$\begin{array}{c} & E \\ & \uparrow \downarrow \\ & M \end{array}$$

such that A is a connection on E with curvature  $\omega$ .

Then

$$\mathcal{L}_{\xi}\psi = \left(\xi^{\mu}D_{\mu} + if\right)\psi$$

and  $\mathcal{H}$  is the space of sections of E. Then a candidate for  $\hat{f}$  is

$$-i\left(\xi^{\mu}D_{\mu}+if\right)$$

and then the inner product between sections is given by

$$\langle \psi | \xi \rangle = \int d \operatorname{Vol} \psi^* \xi$$

Let  $\dim_{\mathbb{R}} M = 2n$ , and assume  $\omega^n$  is a nowhere vanishing 2n-form proportional to d Vol.

In one-dimensional quantum mechanics,  $Q=\mathbb{R},$  so  $M=T^*\mathbb{R}$  with  $\omega=\,dp\wedge dq\,,$   $A=p\,dx\,.$  Then

$$\hat{f} = -i\left(\xi^{\mu}D_{\mu} + if\right)$$

and

$$\hat{q} = i \frac{\partial}{\partial p} + x \qquad \qquad \hat{p} = -i \frac{\partial}{\partial x} \ . \label{eq:phi}$$

Restrict to  $\psi$  such that

$$\frac{\partial \psi}{\partial p}=0$$

We could have made a different choice for f, but we would have gotten isomorphic representations.

But it is unclear how to deal with not being a cotangent bundle. If M is Kähler, we can deal with this since we have a notion of holomorphicity. Being Kähler means we have a metric g and an (almost) complex structure J such that

$$\omega\left(u,v\right) = g\left(Ju,v\right) \ .$$

As a (1, 1) form

$$\begin{split} \omega &= ig_{a\bar{b}} \, dz^a \, \wedge \, d\bar{z}^b \\ &= i\partial \bar{\partial} K \end{split}$$

where K is the (real) Kähler potential. Note that  $\omega = dA$  where

$$A = -\frac{i}{2}\partial_A K \, dz^a + \frac{i}{2}\partial_{\bar{a}} K \, d\bar{z}^a \; .$$

We want solutions of

$$D_{\bar{a}}\psi = 0$$
  $\left(\partial_{\bar{a}} + \frac{1}{2}\partial_{\bar{a}}K\right)\psi = 0$ .

These all look like

$$\psi = e^{-K/2} f\left(z\right)$$

 $\mathbf{2}$ 

where f is some locally holomorphic function. Then we have that the inner product of two sections is:

$$\langle 1|2 \rangle = \int d \operatorname{Vol} e^{-K}$$

**Example 2.** For  $X = \mathbb{R}$ ,  $\omega = i dz \wedge d\overline{z}$ , and  $K = z\overline{z}$ . Then

$$\psi = e^{-\left|z\right|^{2}} f\left(z\right) \; .$$

 $\hat{z}$  is multiplication by z, and  $\hat{\overline{z}} = \partial_z$ . Note that  $[\overline{z}, z] = 1$ , and Hol $(\mathbb{C}) \simeq L^2(\mathbb{R})$ .

In usual quantum mechanics,  $\bar{z}$  would be written as the annihilation operator a, and z would be written as the creation operator  $a^{\dagger}$ . These names can be motivated by considering how they act on a polynomial of a given degree.

**Example 3.** Let  $M = S^2$  with symplectic form

$$\omega = \frac{i\,dz \wedge d\bar{z}}{\left(1+|z|^2\right)^2} \,.$$

Note that

 $\mathbf{so}$ 

$$K = \frac{n}{2} \log \left( 1 + \left| z \right|^2 \right)$$

 $\int_{S^2} \omega = 2\pi$ 

and  $\psi$  is always of the form

(3) 
$$\psi = e^{-K/2} f(z)$$

The inner product is given by

(4) 
$$\langle \psi | 2 \rangle = \frac{i(n+1)}{2\pi} \int \frac{dz \wedge d\bar{z}}{\left(1+|z|^2\right)^{n+2}} f_1^* f_2 .$$

This integral only converges<sup>1</sup> for  $f(z) \sim z^k$  where  $k \in \{0, \ldots, n\}$  which means  $\dim \mathcal{H} = n + 1$ . Recall  $\mathfrak{so}(3)$  acts on  $\mathbb{R}^3 \supset S^2$ . As usual, write

$$J_{+} = \begin{pmatrix} 0 & 0 \\ -1 & 0 \end{pmatrix}$$
$$J_{-} = \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix}$$
$$J_{3} = \frac{1}{2} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

Then this action is given by

$$\hat{J}_{+} = z^{2}\partial_{z} - nz$$
$$\hat{J}_{-} = -\partial_{z}$$
$$\hat{J}_{3} = z\partial_{Z} - \frac{n}{2}$$

So  $\mathcal{H}$  is a representation of SU(2).

In the basis of  $\mathcal{H}$  with basis vectors  $z^k$   $(k \in \{0, \ldots, n\})$  a  $J_3$  eigenvalue of  $z^k$  is k - n/2 for  $k \in \{0, \ldots, n\}$ . This is an (n + 1)-dimensional representation of  $\mathfrak{su}(2)$ .

 $<sup>^1\</sup>mathrm{We}$  could get this dimension by just calculating the dimension of the holomorphic sections for the sphere.

# LECTURE BY ALI SHEHPER

### 3. Chern-Simons theory

Consider Chern-Simons theory for  $G = \mathrm{SU}(2)$  on  $M_3 = \mathbb{R}_+ \times \Sigma_g$ . Then

$$\delta = \frac{k}{2\pi} \int A \, dA \, + \frac{2}{3} A \wedge A \wedge A$$

for  $k \in \mathbb{Z}$ . So we get that the phase space consists of the flat SU (2) connections on  $\Sigma_g$ . The form is given by

(5) 
$$\omega = \frac{k}{4\pi} \int_{\Sigma} \delta A \wedge \delta A \; .$$

Note that dim  $\mathcal{H} = \chi(M, \mathcal{L}^{\otimes k})$ .  $\chi$  is the index of  $\bar{\partial}_{\mathcal{L}^{\otimes k}}$ , which is the integral of the wedge of the Todd class with  $e^{c_1(\mathcal{L})}$ . Then this should be equal to the following:

$$\left(\frac{k+2}{2}\right)^{g-1}\sum_{j=1}^{k+1}\left(\sin\left(\frac{\pi j}{k+2}\right)\right)$$

This is the Verlinde formula.